

Kawasaki dynamics with two types of particles: stable/metastable configurations and communication heights

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Abstract

This is the second in a series of three papers in which we study a two-dimensional lattice gas consisting of two types of particles subject to Kawasaki dynamics at low temperature in a large finite box with an open boundary. Each pair of particles occupying neighboring sites has a negative binding energy provided their types are different, while each particle has a positive activation energy that depends on its type. There is no binding energy between particles of the same type. At the boundary of the box particles are created and annihilated in a way that represents the presence of an infinite gas reservoir. We start the dynamics from the empty box and are interested in the transition time to the full box. This transition is triggered by a critical droplet appearing somewhere in the box.

In the first paper we identified the parameter range for which the system is metastable, showed that the first entrance distribution on the set of critical droplets is uniform, computed the expected transition time up to and including a multiplicative factor of order one, and proved that the nucleation time divided by its expectation is exponentially distributed, all in the limit of low temperature. These results were proved under *three hypotheses*, and involve *three model-dependent quantities*: the energy, the shape and the number of critical droplets. In the second paper we prove the first and the second hypothesis and identify the energy of critical droplets. In the third paper we settle the rest.

Both the second and the third paper deal with understanding the *geometric properties* of subcritical, critical and supercritical droplets, which are crucial in determining the metastable behavior of the system, as explained in the first paper. The geometry turns out to be considerably more complex than for Kawasaki dynamics with one type of particle, for which an extensive literature exists. The main motivation behind our work is to understand metastability of multi-type particle systems.

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1 Introduction

Section 1.1 defines the model, Section 1.2 introduces basic notation, Section 1.3 states the main theorems, while Section 1.4 discusses the main theorems and provides further perspectives.

1.1 Lattice gas subject to Kawasaki dynamics

Let $\Lambda \subset \mathbb{Z}^2$ be a large box centered at the origin (later it will be convenient to choose Λ rhombus-shaped). Let

$$\begin{aligned}\partial^- \Lambda &= \{x \in \Lambda : \exists y \notin \Lambda : |y - x| = 1\}, \\ \partial^+ \Lambda &= \{x \notin \Lambda : \exists y \in \Lambda : |y - x| = 1\},\end{aligned}\tag{1.1}$$

be the internal, respectively, external boundary of Λ , and put $\Lambda^- = \Lambda \setminus \partial^- \Lambda$ and $\Lambda^+ = \Lambda \cup \partial^+ \Lambda$. With each site $x \in \Lambda$ we associate a variable $\eta(x) \in \{0, 1, 2\}$ indicating the absence of a particle or the presence of a particle of type 1 or type 2. A configuration $\eta = \{\eta(x) : x \in \Lambda\}$ is an element of $\mathcal{X} = \{0, 1, 2\}^\Lambda$. To each configuration η we associate an energy given by the Hamiltonian

$$H = -U \sum_{(x,y) \in \Lambda^{*-}} 1_{\{\eta(x)\eta(y)=2\}} + \Delta_1 \sum_{x \in \Lambda} 1_{\{\eta(x)=1\}} + \Delta_2 \sum_{x \in \Lambda} 1_{\{\eta(x)=2\}},\tag{1.2}$$

where $\Lambda^{*-} = \{(x, y) : x, y \in \Lambda^-, |x - y| = 1\}$ is the set of non-oriented bonds inside Λ^- , $-U < 0$ is the *binding energy* between neighboring particles of *different* types inside Λ^- , and $\Delta_1 > 0$ and $\Delta_2 > 0$ are the *activation energies* of particles of type 1, respectively, 2 inside Λ . W.l.o.g. we will assume that

$$\Delta_1 \leq \Delta_2.\tag{1.3}$$

The Gibbs measure associated with H is

$$\mu_\beta(\eta) = \frac{1}{Z_\beta} e^{-\beta H(\eta)}, \quad \eta \in \mathcal{X},\tag{1.4}$$

where $\beta \in (0, \infty)$ is the inverse temperature and Z_β is the normalizing partition sum.

Kawasaki dynamics is the continuous-time Markov process, $(\eta_t)_{t \geq 0}$ with state space \mathcal{X} whose transition rates are

$$c_\beta(\eta, \eta') = e^{-\beta[H(\eta') - H(\eta)]_+}, \quad \eta, \eta' \in \mathcal{X}, \eta \neq \eta', \eta \leftrightarrow \eta',\tag{1.5}$$

where $\eta \leftrightarrow \eta'$ means that η' can be obtained from η by one of the following moves:

- interchanging 0 and 1 or 0 and 2 between two neighboring sites in Λ (“hopping of particles in Λ ”),
- changing 0 to 1 or 0 to 2 in $\partial^- \Lambda$ (“creation of particles in $\partial^- \Lambda$ ”),
- changing 1 to 0 or 2 to 0 in $\partial^- \Lambda$ (“annihilation of particles in $\partial^- \Lambda$ ”),

and $c_\beta(\eta, \eta') = 0$ otherwise. Note that this dynamics preserves particles in Λ , but allows particles to be created and annihilated in $\partial^- \Lambda$. Think of the latter as describing particles entering and exiting Λ along non-oriented bonds between $\partial^+ \Lambda$ and $\partial^- \Lambda$ (the rates of these moves are associated with the bonds rather than with the sites). The pairs (η, η') with $\eta \leftrightarrow \eta'$ are called *communicating configurations*, the transitions between them are called *allowed moves*. Note that particles in $\partial^- \Lambda$ do not interact: the interaction only works in Λ^- .

The dynamics defined by (1.2) and (1.5) models the behavior inside Λ of a lattice gas in \mathbb{Z}^2 , consisting of two types of particles subject to random hopping with hard-core repulsion and with binding between different neighboring types. We may think of $\mathbb{Z}^2 \setminus \Lambda$ as an *infinite reservoir* that keeps

the particle densities fixed at $\rho_1 = e^{-\beta\Delta_1}$ and $\rho_2 = e^{-\beta\Delta_2}$. In the above model this reservoir is replaced by an *open boundary* $\partial^-\Lambda$, where particles are created and annihilated at a rate that matches these densities. Thus, the dynamics is a *finite-state* Markov process, ergodic and reversible with respect to the Gibbs measure μ_β in (1.4).

Note that there is *no* binding energy between neighboring particles of the *same* type. Consequently, the model does *not* reduce to Kawasaki dynamics for one type of particle when $\Delta_1 = \Delta_2$.

1.2 Notation

To state our main theorems in Section 1.3, we need some notation.

Definition 1.1 (a) \square is the configuration where Λ is empty.

(b) \boxplus is the set consisting of the two configurations where Λ is filled with the largest possible checkerboard droplet such that all particles of type 2 are surrounded by particles of type 1.

(c) $\omega: \eta \rightarrow \eta'$ is any path of allowed moves from $\eta \in \mathcal{X}$ to $\eta' \in \mathcal{X}$.

(d) $\Phi(\eta, \eta')$ is the communication height between $\eta, \eta' \in \mathcal{X}$ defined by

$$\Phi(\eta, \eta') = \min_{\omega: \eta \rightarrow \eta'} \max_{\xi \in \omega} H(\xi), \quad (1.6)$$

and $\Phi(A, B)$ is its extension to non-empty sets $A, B \subset \mathcal{X}$ defined by

$$\Phi(A, B) = \min_{\eta \in A, \eta' \in B} \Phi(\eta, \eta'). \quad (1.7)$$

(e) V_η is the stability level of $\eta \in \mathcal{X}$ defined by

$$V_\eta = \Phi(\eta, \mathcal{I}_\eta) - H(\eta), \quad (1.8)$$

where $\mathcal{I}_\eta = \{\xi \in \mathcal{X}: H(\xi) < H(\eta)\}$ is the set of configurations with energy lower than η .

(f) $\mathcal{X}_{\text{stab}} = \{\eta \in \mathcal{X}: H(\eta) = \min_{\xi \in \mathcal{X}} H(\xi)\}$ is the set of stable configurations, i.e., the set of configurations with minimal energy.

(g) $\mathcal{X}_{\text{meta}} = \{\eta \in \mathcal{X}: V_\eta = \max_{\xi \in \mathcal{X} \setminus \mathcal{X}_{\text{stab}}} V_\xi\}$ is the set of metastable configurations, i.e., the set of non-stable configurations with maximal stability level.

(h) $\Gamma = V_\eta$ for $\eta \in \mathcal{X}_{\text{meta}}$ (note that $\eta \mapsto V_\eta$ is constant on $\mathcal{X}_{\text{meta}}$), $\Gamma^* = \Phi(\square, \boxplus) - H(\square)$ (note that $H(\square) = 0$).

In [3] we were interested in the transition of the Kawasaki dynamics from \square to \boxplus in the limit as $\beta \rightarrow \infty$. This transition, which is viewed as a crossover from a “gas phase” to a “liquid phase”, is triggered by the appearance of a *critical droplet* somewhere in Λ . The critical droplets form a subset of the set of configurations realizing the energetic minimax of the paths of the Kawasaki dynamics from \square to \boxplus , which all have energy Γ^* because $H(\square) = 0$.

In [3] we showed that the first entrance distribution on the set of critical droplets is uniform, computed the expected transition time up to and including a multiplicative factor of order one, and proved that the nucleation time divided by its expectation is exponentially distributed, all in the limit as $\beta \rightarrow \infty$. These results, which are typical for metastable behavior, were proved under *three hypotheses*:

(H1) $\mathcal{X}_{\text{stab}} = \boxplus$.

(H2) There exists a $V^* < \Gamma^*$ such that $V_\eta \leq V^*$ for all $\eta \in \mathcal{X} \setminus \{\square, \boxplus\}$.

(H3) A hypothesis about the shape of the configurations in the essential gate for the transition from \square to \boxplus (for details see [3]).

Hypotheses (H1–H3) are the *geometric input* that is needed to derive the main theorems in [3] with the help of the *potential-theoretic approach* to metastability as outlined in Bovier [2]. In the present paper we prove (H1–H2) and identify the energy Γ^* of critical droplets. In [4] we settle the rest.

Lemma 1.2 (H1–H2) *imply that $V_{\square} = \Gamma^*$, and hence that $\mathcal{X}_{\text{meta}} = \square$ and $\Gamma = \Gamma^*$.*

Proof. By Definition 1.1(e–h) and (H1), $\boxplus \in \mathcal{I}_{\square}$, which implies that $V_{\square} \leq \Gamma^*$. We show that (H2) implies $V_{\square} = \Gamma^*$. The proof is by contradiction. Suppose that $V_{\square} < \Gamma^*$. Then, by Definition 1.1(h), there exists a $\eta_0 \in \mathcal{I}_{\square} \setminus \boxplus$ such that $\Phi(\square, \eta_0) - H(\square) < \Gamma^*$. But (H2), together with the finiteness of \mathcal{X} , implies that there exist an $m \in \mathbb{N}$ and a sequence $\eta_1, \dots, \eta_m \in \mathcal{X}$ with $\eta_m = \boxplus$ such that $\eta_{i+1} \in \mathcal{I}_{\eta_i}$ and $\Phi(\eta_i, \eta_{i+1}) \leq H(\eta_i) + V^*$ for $i = 0, \dots, m-1$. Therefore

$$\Phi(\eta_0, \boxplus) \leq \max_{i=0, \dots, m-1} \Phi(\eta_i, \eta_{i+1}) \leq \max_{i=0, \dots, m-1} [H(\eta_i) + V^*] = H(\eta_0) + V^* < H(\square) + \Gamma^*, \quad (1.9)$$

where in the first inequality we use that $\Phi(\eta, \sigma) \leq \max\{\Phi(\eta, \xi), \Phi(\xi, \sigma)\}$ for all $\eta, \sigma, \xi \in \mathcal{X}$, and in the last inequality that $\eta_0 \in \mathcal{I}_{\square}$ and $V^* < \Gamma^*$. It follows that

$$\Phi(\square, \boxplus) - H(\square) \leq \max\{\Phi(\square, \eta_0) - H(\square), \Phi(\eta_0, \boxplus) - H(\square)\} < \Gamma^*, \quad (1.10)$$

which contradicts Definition 1.1(h). Observe that the proof uses that $\mathcal{X}_{\text{meta}}$ consists of a single configuration. \blacksquare

Hypotheses (H1–H2) imply that $(\mathcal{X}_{\text{meta}}, \mathcal{X}_{\text{stab}}) = (\square, \boxplus)$, and that the highest energy barrier between any two configurations in \mathcal{X} is the one separating \square and \boxplus , i.e., (\square, \boxplus) is the unique *metastable pair*. Hypothesis (H3) is needed only to find the asymptotics of the prefactor of the expected transition time in the limit as $\Lambda \rightarrow \mathbb{Z}^2$. The main theorems in [3] involve *three model-dependent quantities*: the energy, the shape and the number of critical droplets.

1.3 Main theorems

In [3] it was shown that $\Delta_1 + \Delta_2 < 4U$ is the *metastable region*, i.e., the region of parameters for which \square is a local minimum but not a global minimum of H . Moreover, it was argued that within this region the subregion where $\Delta_1, \Delta_2 < U$ is of no interest because the critical droplet consists of two free particles, one of type 1 and one of type 2. Therefore the *proper metastable region* is

$$0 < \Delta_1 \leq \Delta_2, \quad \Delta_1 + \Delta_2 < 4U, \quad \Delta_2 \geq U, \quad (1.11)$$

as indicated in Fig. 1.

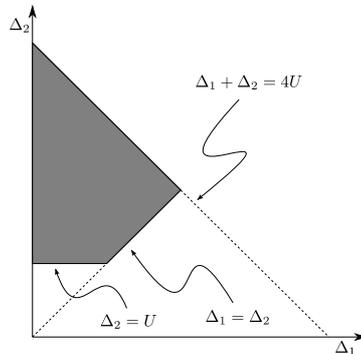


Figure 1: Proper metastable region.

In this present paper, the analysis will be carried out for the subregion where

$$0 < \Delta_1 < U, \quad \Delta_2 - \Delta_1 > 2U, \quad \Delta_1 + \Delta_2 < 4U, \quad (1.12)$$

as indicated in Fig. 2. *Note:* The second and third restriction imply the first restriction. Nevertheless, we write all three because each plays an important role in the sequel.

The following three theorems are the main result of the present paper and are valid subject to (1.12). We write $\lceil \cdot \rceil$ to denote the upper integer part.

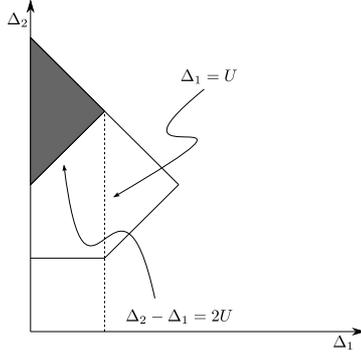


Figure 2: Subregion of the proper metastable region given by (1.12).

Theorem 1.3 $\mathcal{X}_{\text{stab}} = \boxplus$.

Theorem 1.4 *There exists a $V^* \leq 10U - \Delta_1$ such that $V_\eta \leq V^*$ for all $\eta \in \mathcal{X} \setminus \{\square, \boxplus\}$. Consequently, if $\Gamma^* > 10U - \Delta_1$, then $\mathcal{X}_{\text{meta}} = \square$ and $\Gamma = \Gamma^*$.*

Theorem 1.5 $\Gamma^* = -[\ell^*(\ell^* - 1) + 1](4U - \Delta_1 - \Delta_2) + (2\ell^* + 1)\Delta_1 + \Delta_2$ with

$$\ell^* = \left\lceil \frac{\Delta_1}{4U - \Delta_1 - \Delta_2} \right\rceil \in \mathbb{N}. \quad (1.13)$$

Theorem 1.3 settles hypothesis (H1) in [3], Theorem 1.4 settles hypothesis (H2) in [3] when $\Gamma^* > 10U - \Delta_1$, while Theorem 1.5 identifies Γ^* .

As soon as $V^* < \Gamma^*$, the energy landscape does not contain wells deeper than those surrounding \square and \boxplus . Theorems 1.3 and 1.4 imply that this occurs at least when $\Gamma^* > 10U - \Delta_1$, while Theorem 1.5 identifies Γ^* and allows us to exhibit a further subregion of (1.12) where the latter inequality is satisfied. This further subregion contains the shaded region in Fig. 3.

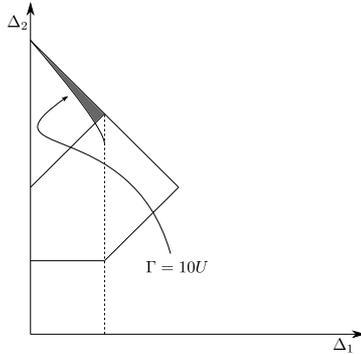


Figure 3: The parameter region where $\Gamma^* > 10U - \Delta_1$ contains the shaded region.

1.4 Discussion

1. In Section 4 we will see that the *critical droplets* for the crossover from \square to \boxplus consist of a *rhombus-shaped checkerboard with a protuberance plus a free particle*, as indicated in Fig. 4. A more detailed description will be given in [4].

2. Abbreviate

$$\varepsilon = 4U - \Delta_1 - \Delta_2 \quad (1.14)$$

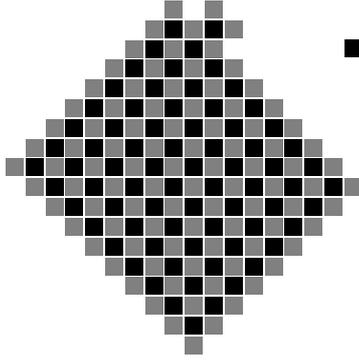


Figure 4: A critical droplet. Light-shaded squares are particles of type 1, dark-shaded squares are particles of type 2. The particles of type 2 form an $\ell^* \times (\ell^* - 1)$ quasi-square with a protuberance attached to one of its longest sides, and are all surrounded by particles of type 1. In addition, there is a free particle of type 2. As soon as this free particle attaches itself “properly” to a particle of type 1 the dynamics is “over the hill” (see [3], Section 2.3, item 3).

and write $\ell^* = (\Delta_1/\varepsilon) + \iota$ with $\iota \in [0, 1)$. Then an easy computation shows that $\Gamma^* = (\Delta_1)^2/\varepsilon + \Delta_1 + 4U + \varepsilon\iota(1 - \iota)$. From this we see that

$$\ell^* \sim \Delta_1/\varepsilon, \quad \Gamma^* \sim (\Delta_1)^2/\varepsilon, \quad \varepsilon \downarrow 0. \quad (1.15)$$

The limit $\varepsilon \downarrow 0$ corresponds to the *weakly supersaturated* regime, where the lattice gas wants to condensate but the energetic threshold to do so is high (because the critical droplet is large). From the viewpoint of metastability this regime is the most interesting. The shaded region in Fig. 3 captures this regime for all $0 < \Delta_1 < U$. This region contains the set of parameters where $(\Delta_1)^2/\varepsilon + \Delta_1 + 4U > 10U - \Delta_1$, i.e., $\varepsilon/U < (\Delta_1/U)^2/[6 - 2(\Delta_1/U)]$.

3. The simplifying features of (1.12) over (1.11) are the following: $\Delta_1 < U$ implies that each time a particle of type 1 enters Λ and attaches itself to a particle of type 2 in a droplet the energy goes down, while $\Delta_2 - \Delta_1 > 2U$ implies that no particle of type 2 sits on the boundary of a droplet that has minimal energy given the number of particles of type 2 in the droplet. In [3] we conjectured that the metastability results presented there actually hold throughout the region given by (1.11), even though the critical droplets will be *different* when $\Delta_1 \geq U$.

As will become clear in Section 3, the constraint $\Delta_1 < U$ has the effect that in all configurations that are local minima of H all particles on the boundary of a droplet are of type 1. It will turn out that such configurations consist of a single *rhombus-shaped checkerboard droplet*. We expect that as Δ_1 increases from U to $2U$ there is a gradual transition from a rhombus-shaped checkerboard critical droplet to a square-shaped checkerboard critical droplet. This is one of the reasons why it is difficult to go beyond (1.12).

4. What makes Theorem 1.4 hard to prove is that the estimate on V_η has to be uniform in $\eta \notin \{\square, \boxplus\}$. In configurations containing several droplets and/or droplets close to $\partial^- \Lambda$ there may be a lack of free space making the motion of particles inside Λ difficult. The mechanisms developed in Section 5 allow us to realize an *energy reduction* to a configuration that lies on a suitable *reference path for the nucleation* within an energy barrier $10U - \Delta_1$ also in the absence of free space around each droplet.

We will see in Section 5 that for droplets sufficiently far away from other droplets and from $\partial^- \Lambda$ a reduction within an energy barrier $\leq 4U + \Delta_1$ is possible. Thus, if we would be able to control the configurations that fail to have this property, then we would have $V^* \leq 4U + \Delta_1$ and, consequently, would have $\mathcal{X}_{\text{meta}} = \square$ and $\Gamma = \Gamma^*$ throughout the subregion given by (1.12) because $\Gamma^* > 4U + \Delta_1$.

Another way of phrasing the last observation is the following. We view the “liquid phase” as the configuration filling the entire box Λ . If, instead, we would let the liquid phase correspond to the set

of configurations filling most of Λ but staying away from $\partial^-\Lambda$, then the metastability results derived in [3] would apply throughout the subregion given by (1.12).

5. Theorems 1.3 and 1.5 can actually be proved *without* the restriction $\Delta_2 - \Delta_1 > 2U$. However, removal of this restriction makes the task of showing that in droplets with minimal energy all particles of type 2 are surrounded by particles of type 1 more involved than what is done in Section 3. We omit this extension, since the restriction $\Delta_2 - \Delta_1 > 2U$ is needed for Theorem 1.4 anyway.

Outline. Section 2 contains preparations. Theorems 1.3–1.5 are proved in Sections 3–5, respectively. The proofs are *purely combinatorial*, and are rather involved due to the presence of two types of particles rather than one. Sections 3–4 deal with *statics* and Section 5 with *dynamics*. Section 5 is technically the hardest and takes up about half of the paper. More detailed outlines are given at the beginning of each section.

2 Coordinates, definitions and polyominoes

Section 2.1 introduces two coordinate systems that are used to describe the particle configurations: standard and dual. Section 2.2 lists the main geometric definitions that are needed in the rest of the paper. Section 2.3 proves a lemma about polyominoes (finite unions of unit squares) and Section 2.4 a lemma about 2-tiled clusters (checkerboard configurations where all particles of type 2 are surrounded by particles of type 1). These lemmas are needed in Section 3 to identify the droplets of minimal energy given the number of particles of type 2 in Λ .

2.1 Coordinates

1. A site $i \in \Lambda$ is identified by its *standard coordinates* $(x_1(i), x_2(i))$, and is called odd when $x_1(i) + x_2(i)$ is odd and even when $x_1(i) + x_2(i)$ is even. The standard coordinates of a particle p in Λ are denoted by $x(p) = (x_1(p), x_2(p))$. The *parity* of a particle p is defined as $x_1(p) + x_2(p) + \eta(x(p))$ modulo 2, and p is said to be odd when the parity is 1 and even when the parity is 0.

2. A site $i \in \Lambda$ is also identified by its *dual coordinates*

$$u_1(i) = \frac{x_1(i) - x_2(i)}{2}, \quad u_2(i) = \frac{x_1(i) + x_2(i)}{2}. \quad (2.1)$$

Two sites i and j are said to be *adjacent*, written $i \sim j$, when $|x_1(i) - x_1(j)| + |x_2(i) - x_2(j)| = 1$ or, equivalently, $|u_1(i) - u_1(j)| = |u_2(i) - u_2(j)| = \frac{1}{2}$ (see Fig. 5).

3. For convenience, we take Λ to be the $(L + \frac{3}{2}) \times (L + \frac{3}{2})$ dual square centered at the origin for some $L \in \mathbb{N}$ with $L > 2\ell^*$ (to allow for $H(\boxplus) < H(\square)$; see Section 3.1). Particles interact only inside Λ^- , which is the $(L + \frac{1}{2}) \times (L + \frac{1}{2})$ dual square centered at the origin. This dual square, a *rhombus* in standard coordinates, is convenient because the local minima of H are rhombus-shaped as well (see Section 3).

2.2 Definitions

1. A site $i \in \Lambda$ is said to be *lattice-connecting* in the configuration η if there exists a lattice path λ from i to $\partial^-\Lambda$ such that $\eta(j) = 0$ for all $j \in \lambda$ with $j \neq i$. We say that a particle p is lattice-connecting if $x(p)$ is a lattice-connecting site.

2. Two particles in η at sites i and j are called *connected* if $i \sim j$ and $\eta(i)\eta(j) = 2$. If two particles p_1 and p_2 are connected, then we say that there is an *active bond* b between them. The bond b is said to be *incident* to p_1 and p_2 . A particle p is said to be *saturated* if it is connected to four other particles, i.e., there are four active bonds incident to p . The support of the configuration η , i.e., the union of the

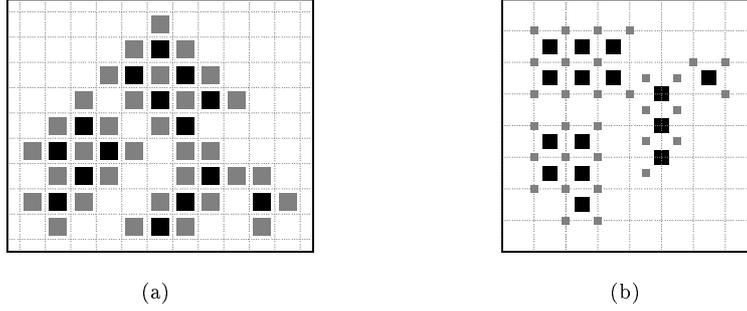


Figure 5: A configuration represented in: (a) standard coordinates; (b) dual coordinates. Light-shaded squares are particles of type 1, dark-shaded squares are particles of type 2. In dual coordinates, particles of type 2 are represented by larger squares than particles of type 1 to exhibit the “tiled structure” of the configuration.

unit squares centered at the occupied sites of η , is denoted by $\text{supp}(\eta)$. For a configuration η , $n_1(\eta)$ and $n_2(\eta)$ denote the number of particles of type 1 and 2 in η , and $B(\eta)$ denotes the number of active bonds. The energy of η equals $H(\eta) = \Delta_1 n_1(\eta) + \Delta_2 n_2(\eta) - UB(\eta)$.

3. Let $G(\eta)$ be the *graph* associated with η , i.e., $G(\eta) = (V(\eta), E(\eta))$, where $V(\eta)$ is the set of sites $i \in \Lambda$ such that $\eta(i) \neq 0$, and $E(\eta)$ is the set of the pairs $\{i, j\}$, $i, j \in V(\eta)$, such that the particles at sites i and j are connected. A configuration η' is called a *subconfiguration* of η , written $\eta' \prec \eta$, if $\eta'(i) = \eta(i)$ for all $i \in \Lambda$ such that $\eta'(i) > 0$. A subconfiguration $c \prec \eta$ is a *cluster* if the graph $G(c)$ is a maximal connected component of $G(\eta)$. The set of non-saturated particles in c is called the *boundary* of c , and is denoted by ∂c . Clearly, all particles in the same cluster have the same parity. Therefore the concept of parity extends from particles to clusters.

4. For a site $i \in \Lambda$, the *tile* centered at i , denoted by $t(i)$, is the set of five sites consisting of i and the four sites adjacent to i . If i is an even site, then the tile is said to be even, otherwise the tile is said to be odd. The five sites of a tile are labeled a, b, c, d, e as in Fig. 6. The sites labeled a, b, c, d are called *junction sites*. If a particle p sits at site i , then $t(i)$ is also denoted by $t(p)$ and is called the tile associated with p . In standard coordinates, a tile is a square of size $\sqrt{2}$. In dual coordinates, it is a unit square.

5. A tile whose central site is occupied by a particle of type 2 and whose junction sites are occupied by particles of type 1 is called a *2-tile* (see Fig. 6). Two 2-tiles are said to be adjacent if their particles of type 2 have dual distance 1. A horizontal (vertical) *12-bar* is a maximal sequence of adjacent 2-tiles all having the same horizontal (vertical) coordinate. If the sequence has length 1, then the 12-bar is called a *2-tiled protuberance*. A cluster containing at least one particle of type 2 such that all particles of type 2 are saturated is said to be 2-tiled. A 2-tiled configuration is a configuration consisting of 2-tiled clusters only.

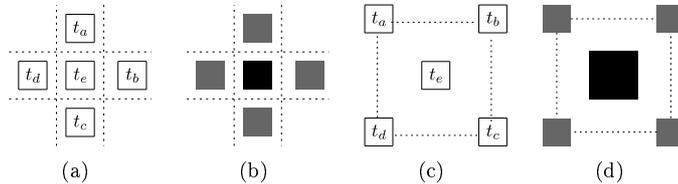


Figure 6: Tiles: (a) standard representation of the labels of a tile; (b) standard representation of a 2-tile; (c) dual representation of the labels of a tile; (d) dual representation of a 2-tile.

6. The *tile support* of a configuration η is defined as

$$[\eta] = \bigcup_{p \in \varpi_2(\eta)} t(p), \quad (2.2)$$

where $\varpi_2(\eta)$ is the set of particles of type 2 in η . Obviously, $[\eta]$ is the union of the tile supports of the clusters making up η . For a standard cluster c the *dual perimeter*, denoted by $P(c)$, is the length of the Euclidean boundary of its tile support $[c]$ (which includes an inner boundary when c contains holes). The dual perimeter $P(\eta)$ of a 2-tiled configuration η is the sum of the dual perimeters of the clusters making up η .

7. \mathcal{V}_{\star, n_2} is the set of configurations such that in Λ^{--} the number of particles of type 2 is n_2 . $\mathcal{V}_{\star, n_2}^{4n_2}$ is the set of configurations such that in Λ^{--} the number of particles of type 2 is n_2 , the number of active bonds is $4n_2$, and there is no isolated particle of type 1. In other words, $\mathcal{V}_{\star, n_2}^{4n_2}$ is the set of 2-tiled configurations with n_2 particles of type 2. The lower index \star is used to indicate that configurations in these sets can have an arbitrary number of particles of type 1. A configuration η is called *standard* if $\eta \in \mathcal{V}_{\star, n_2}^{4n_2}$, and its tile support is a standard polyomino in dual coordinates (see Definition 2.1 below for the definition of a standard polyomino).

8. A *unit hole* is an empty site such that all four of its neighbors are occupied by particles of the same type (either all of type 1 or all of type 2). An empty site with three neighboring sites occupied by a particle of type 1 is called a *good dual corner*. In the dual representation a good dual corner is a concave corner (see Fig. 7).

2.3 A lemma on polyominoes

The tile support of a cluster c can be represented by a polyomino, i.e., a finite union of unit squares. The following notation is used:

$\ell_1(c)$ = width of c (= number of columns).

$\ell_2(c)$ = height of c (= number of rows).

$v_i(c)$ = number of vertical edges in the i -th non-empty row of c .

$h_j(c)$ = number of horizontal edges in the j -th non-empty column of c .

$P(c)$ = length of the perimeter of c .

$Q(c)$ = number of holes in c .

$\psi(c)$ = number of convex corners of c .

$\phi(c)$ = number of concave corners of c .

Note that $\psi(c) = \sum_{i=1}^{N(c)} \psi(i)$ and $\phi(c) = \sum_{i=1}^{N(c)} \phi(i)$, where $N(c)$ is the number of vertices in the polyomino representing c . If two edges e_1 and e_2 are incident to vertex i at a right angle with a unit square inside and no unit squares outside, then $\psi(i) = 1$ and $\phi(i) = 0$ (Fig. 7(a)). On the other hand, if there is no unit square inside and three unit squares outside, then $\psi(i) = 0$ and $\phi(i) = 1$ (Fig. 7(b)). If four edges e_1, e_2, e_3, e_4 are incident to vertex i , with two unit squares in opposite angles, then $\psi(i) = 0$ and $\phi(i) = 2$ (Fig. 7(c)).

Definition 2.1 [Alonso and Cerf [1].] *A polyomino is called monotone if its perimeter is equal to the perimeter of its circumscribing rectangle. A polyomino whose support is a quasi-square (i.e., a rectangle whose side lengths differ by at most one), with possibly a bar attached to one of its longest sides, is called a standard polyomino.*

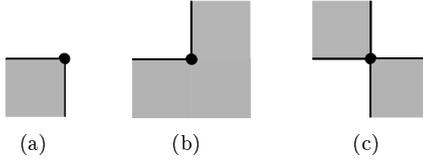


Figure 7: Corners of polyominoes: (a) one convex corner; (b) one concave corner; (c) two concave corners. Shaded mean occupied by a unit square.

In the sequel, a key role will be played by the quantity

$$\mathcal{T}(c) = 2P(c) + [\psi(c) - \phi(c)] = 2P(c) + 4 - 4Q(c). \quad (2.3)$$

Lemma 2.2 (i) *All polyominoes c with a fixed number of monominoes minimizing $\mathcal{T}(c)$ are single-component monotone polyominoes of minimal perimeter, which include the standard polyominoes.*
(ii) *If the number of monominoes is ℓ^2 , $\ell^2 - 1$, $\ell(\ell - 1)$ or $\ell(\ell - 1) - 1$ for some $\ell \in \mathbb{N} \setminus \{1\}$, then the standard polyominoes are the only minimizers of $\mathcal{T}(c)$.*

Proof. In the proof we assume w.l.o.g. that the polyomino consists of a single cluster c .

(i) The proof uses projection. Pick any non-monotone cluster c . Let

$$\tilde{c} = (\pi_2 \circ \pi_1)(c), \quad (2.4)$$

where π_2 and π_1 denote the vertical, respectively, the horizontal projection of c . The effect of vertical and horizontal projection is illustrated in Fig. 8. By construction, \tilde{c} is a monotone polyomino (see e.g. the statement on Ferrers diagrams in the proof of Alonso and Cerf [1], Theorem 2.2).

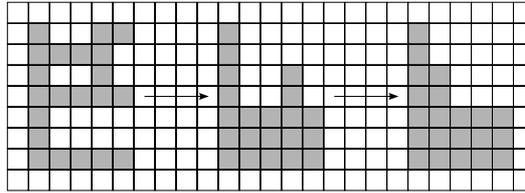


Figure 8: Effect of vertical and horizontal projection.

Suppose first that $Q(c) = 0$. Then $\mathcal{T}(c) = 2P(c) + 4$. Since c is not monotone, we have $P(\tilde{c}) < P(c)$, and so c is not a minimizer of $\mathcal{T}(c)$.

Suppose next that $Q(c) \geq 1$. Since

$$P(c) = \sum_{i=1}^{\ell_2(c)} v_i(c) + \sum_{j=1}^{\ell_1(c)} h_j(c) \quad (2.5)$$

and every hole belongs to at least one row and one column, we have

$$P(c) \geq 2[\ell_1(c) + \ell_2(c)] + 4Q(c). \quad (2.6)$$

On the other hand, since \tilde{c} is a monotone polyomino, we have $v_i(\tilde{c}) = h_j(\tilde{c}) = 2$ for all i and j , and so

$$P(\tilde{c}) = 2[\ell_1(\tilde{c}) + \ell_2(\tilde{c})]. \quad (2.7)$$

Moreover, since $\ell_1(\tilde{c}) \leq \ell_1(c)$ and $\ell_2(\tilde{c}) \leq \ell_2(c)$, we can combine (2.6–2.7) to get

$$P(\tilde{c}) - P(c) \leq -4Q(c), \quad (2.8)$$

Using (2.8), we obtain

$$\mathcal{T}(\tilde{c}) - \mathcal{T}(c) = [2P(\tilde{c}) + 4] - [2P(c) + 4 - 4Q(c)] = 2[P(\tilde{c}) - P(c)] + 4Q(c) \leq -4Q(c) \leq -4 < 0, \quad (2.9)$$

and so c is not a minimizer of $\mathcal{T}(c)$.

(ii) We saw in the proof of (i) that if c is a minimizer of $\mathcal{T}(c)$, then c is monotone, and hence does not contain holes and minimizes $P(c)$. The claim therefore follows from Alonso and Cerf [1], Corollary 3.7, which states that if the number of monominoes is ℓ^2 , $\ell^2 - 1$, $\ell(\ell - 1)$ or $\ell(\ell - 1) - 1$ for some $\ell \in \mathbb{N} \setminus \{1\}$, then the standard polyominoes are the only minimizers of $P(c)$. ■

2.4 Relation between \mathcal{T} and the number of missing bonds in 2-tiled clusters

In this section we consider 2-tiled clusters and link the number of particles of type 1 and type 2 to the number of active bonds and the geometric quantity \mathcal{T} considered in Section 2.3.

Lemma 2.3 *For any 2-tiled cluster c (i.e., $c \in \mathcal{V}_{\star, n_2}^{4n_2}$ for some n_2), $4n_1(c) = B(c) + \mathcal{T}(c)$ and $4n_2(c) = B(c)$.*

Proof. The claim of the lemma is equivalent to the affirmation that $\mathcal{T}(c) = M(c)$ with $M(c)$ the number of missing bonds in c . Indeed, informally, for every unit perimeter two bonds are lost with respect to the four bonds that would be incident to each particle of type 1 if it were saturated, while one bond is lost at each convex corner and one bond is gained at each concave corner.

Formally, let p be a particle of type 1, $B(p)$ the number of bonds incident to p , and $M(p) = 4 - B(p)$ the number of missing bonds of p . Consider the set of particles of type 1 at the boundary of a 2-tiled cluster, i.e., the set of non-saturated particles of type 1. Each of these particles belongs to one of four classes (see Fig. 9):

- class 1: p has two neighboring particles of type 2 belonging to the same 12-bar.
- class 2: p has two neighboring particles of type 2 belonging to different 12-bars.
- class 3: p has three neighboring particles of type 2.
- class 4: p has one neighboring particle of type 2.

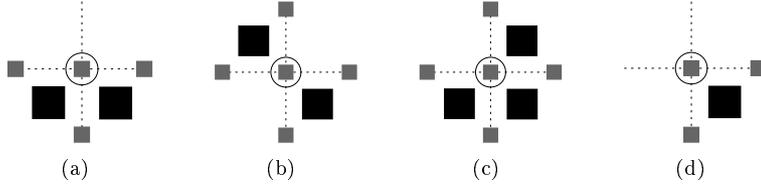


Figure 9: The circled boundary particle of type 1 belongs to: (a) class 1; (b) class 2; (c) class 3; (d) class 4.

Let $M_k(c)$ be the number of missing bonds of particles of class k in cluster c , and $A_k(c)$ the number of edges incident to particles of class k in cluster c . Then

$$M_1(c) = 2, A_1(c) = 2; \quad M_2(c) = 2, A_2(c) = 4; \quad M_3(c) = 1, A_3(c) = 2; \quad M_4(c) = 3, A_4(c) = 2. \quad (2.10)$$

Let $N_k(c)$ be the number of particles of class k of type 1 in cluster c . Observing that a cluster has two concave corners per particle of class 2, one concave corner per particle of class 3 and one convex corner per particle of class 4, we can write

$$\mathcal{T}(c) = 2P(c) - 2N_2(c) - N_3(c) + N_4(c). \quad (2.11)$$

Since the dual perimeter of a cluster is equal to its total number of dual edges, we have

$$2P(c) = \sum_{k=1}^4 A_k(c)N_k(c) = 2N_1(c) + 4N_2(c) + 2N_3(c) + 2N_4(c) \quad (2.12)$$

(the sum counts each edge of the 2-tile twice). The total number of missing bonds, on the other hand, is

$$M(c) = \sum_{k=1}^4 M_k(c)N_k(c) = 2N_1(c) + 2N_2(c) + N_3(c) + 3N_4(c). \quad (2.13)$$

Combining (2.11–2.13), we arrive at $\mathcal{T}(c) = M(c)$. ■

3 Proof of Theorem 1.3: identification of $\mathcal{X}_{\text{stab}}$

Recall that Λ^- (the part of Λ where particles interact) is an $(L + \frac{1}{2}) \times (L + \frac{1}{2})$ dual square with $L > 2\ell^*$. Let $\eta_{\text{stab}}, \eta'_{\text{stab}}$ be the configurations consisting of a 2-tiled dual square of size L with even parity, respectively, odd parity. These two configurations have the same energy. Theorem 1.3 says that $\mathcal{X}_{\text{stab}} = \{\eta_{\text{stab}}, \eta'_{\text{stab}}\} = \boxplus$. Section 3.1 contains two lemmas about 2-tiled configurations with minimal energy. Section 3.2 uses these two lemmas to prove Theorem 1.3.

3.1 Standard configurations are minimizers among 2-tiled configurations

Lemma 3.1 *Within $\mathcal{V}_{\star, n_2}^{4n_2}$, the standard configurations achieve the minimal energy.*

Proof. Recall from item 2 in Section 2.2 that

$$H(\eta) = \Delta_1 n_1(\eta) + \Delta_2 n_2(\eta) - UB(\eta). \quad (3.1)$$

In $\mathcal{V}_{\star, n_2}^{4n_2}$ both n_2 and $B = 4n_2$ are fixed, and hence $\min_{\eta \in \mathcal{V}_{\star, n_2}^{4n_2}} H(\eta)$ is attained at a configuration minimizing n_1 . By Lemma 2.3, if $\eta \in \mathcal{V}_{\star, n_2}^{4n_2}$, then

$$n_1(\eta) = \frac{1}{4}[B(\eta) + \mathcal{T}(\eta)], \quad n_2(\eta) = \frac{1}{4}B(\eta). \quad (3.2)$$

Hence, to minimize $n_1(\eta)$ we must minimize $\mathcal{T}(\eta)$. The claim therefore follows from Lemma 2.2(i). ■

For a standard configuration the computation of the energy is straightforward. For $\ell \in \mathbb{N}$, $\zeta \in \{0, 1\}$ and $k \in \mathbb{N}_0$ with $k \leq \ell + \zeta$, let $\eta^{\ell, \zeta, k}$ denote the standard configuration consisting of an $\ell \times (\ell + \zeta)$ (quasi-)square with a bar of length k attached to one of its longest sides (see Fig. 10).

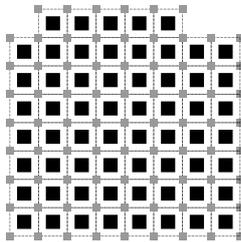


Figure 10: A standard configuration with $\ell = 7, \zeta = 1$ and $k = 5$.

Lemma 3.2 *The energy of $\eta^{\ell, \zeta, k}$ is (recall (1.14))*

$$H(\eta^{\ell, \zeta, k}) = -\varepsilon[\ell(\ell + \zeta) + k] + \Delta_1[\ell + (\ell + \zeta) + 1 + 1_{\{k > 0\}}]. \quad (3.3)$$

Proof. Note that $P(\eta^{\ell,\zeta,k}) = 2[\ell + (\ell + \zeta) + 1_{\{k>0\}}]$ and $Q(\eta^{\ell,\zeta,k}) = 0$, so that

$$\mathcal{T}(\eta^{\ell,\zeta,k}) = 4[\ell + (\ell + \zeta) + 1 + 1_{\{k>0\}}]. \quad (3.4)$$

Also note that

$$B(\eta^{\ell,\zeta,k}) = 4[\ell + (\ell + \zeta) + k], \quad (3.5)$$

because all particles of type 2 are saturated. However, by (3.1–3.2), we have

$$H(\eta^{\ell,\zeta,k}) = -\frac{1}{4}\varepsilon B(\eta^{\ell,\zeta,k}) + \frac{1}{4}\mathcal{T}(\eta^{\ell,\zeta,k})\Delta_1, \quad (3.6)$$

and so the claim follows by combining (3.4–3.6). \blacksquare

Note that the energy increases by $\Delta_1 - \varepsilon$ (which is > 0 if and only if $\ell^* \geq 2$ by (1.13)) when a bar of length $k = 1$ is added, and decreases by ε each time the bar is extended. Note further that

$$H(\eta^{\ell,1,0}) - H(\eta^{\ell,0,0}) = \Delta_1 - \ell\varepsilon, \quad H(\eta^{\ell+1,0,0}) - H(\eta^{\ell,1,0}) = \Delta_1 - (\ell + 1)\varepsilon, \quad (3.7)$$

which show that the energy of a growing sequence of standard configurations goes up when $\ell < \ell^*$ and goes down when $\ell \geq \ell^*$. The highest energy is attained at $\eta^{\ell^*-1,1,1}$, which is the critical droplet in Fig. 4.

It is worth noting that $H(\eta_s^{2\ell^*,0,0}) < 0$, i.e., the energy of a dual square of side length $2\ell^*$ is lower than the energy of \square . This is why we assumed $L > 2\ell^*$, to allow for $H(\boxplus) < H(\square)$.

3.2 Stable configurations

In this section we use Lemmas 3.1–3.2 to prove Theorem 1.3.

Proof. Let η denote any configuration in $\mathcal{X}_{\text{stab}}$. Below we will show that:

- (A) η does not contain any particle in $\partial^-\Lambda$.
- (B) η is a 2-tiled configuration, i.e., $\eta \in \mathcal{V}_{\star,n_2}^{4n_2}$ for some $n_2 (= n_2(\eta))$.

Once we have (A) and (B), we observe that η cannot contain a number of 2-tiles larger than L^2 . Indeed, consider the tile support of η . Since Λ^- is an $(L + \frac{1}{2}) \times (L + \frac{1}{2})$ dual square, if the tile support of η fits inside Λ^- , then so does the dual circumscribing rectangle of η . But any rectangle of area $\geq L^2$ has at least one side of length $L + 1$. Hence $n_2(\eta) \leq L^2$, and therefore the number of 2-tiles in η is at most L^2 . By Lemmas 3.1–3.2, the global minimum of the energy is attained at the largest dual quasi-square that fits inside Λ^- , since $L > 2\ell^*$. We therefore conclude that $\eta \in \{\eta_{\text{stab}}, \eta'_{\text{stab}}\}$, which proves the claim.

Proof of (A). Since in $\partial^-\Lambda$ particles do not feel any interaction but have a positive energy cost, removal of a particle from $\partial^-\Lambda$ always lowers the energy.

Proof of (B). We note the following three facts:

- (1) η does not contain isolated particles of type 1.
- (2) $\partial^-\Lambda^-$ does not contain any particle of type 2.
- (3) All particles of type 2 in η have all their neighboring sites occupied by a particle.

For (1), simply note that the configuration obtained from η by removing isolated particles has lower energy. For (2), note that particles in $\partial^-\Lambda^-$ have at most two active bonds. Therefore, if η would have a particle of type 2 in $\partial^-\Lambda^-$, then the removal of that particle would lower the energy, because $\Delta_2 - \Delta_1 > 2U$ and $\Delta_1 > 0$ (recall (1.12)) imply $\Delta_2 > 2U$. For (3), note that if a particle of type 2

has an empty neighboring site, then the addition of a particle of type 1 at this site lowers the energy, because $\Delta_1 < U$ (recall (1.12)).

We can now complete the proof of (B) as follows. The constraint $\Delta_2 - \Delta_1 > 2U$ implies that any particle of type 2 in η must have at least three neighboring sites occupied by a particle of type 1. Indeed, the removal of a particle of type 2 with at most two active bonds lowers the energy. But the fourth neighboring site must also be occupied by a particle of type 1. Indeed, suppose that this site would be occupied by a particle of type 2. Then this particle would have at most three active bonds. Consider the configuration $\tilde{\eta}$ obtained from η after replacing this particle by a particle of type 1. Then $B(\tilde{\eta}) - B(\eta) \geq -2$, $n_1(\tilde{\eta}) - n_1(\eta) = 1$ and $n_2(\tilde{\eta}) - n_2(\eta) = -1$. Consequently, $H(\tilde{\eta}) - H(\eta) \leq \Delta_1 - \Delta_2 + 2U < 0$. Hence, any particle of type 2 in η must be saturated. ■

4 Proof of Theorem 1.5: identification of $\Gamma^* = \Phi(\square, \boxplus)$

In Section 4.1 we prove Theorem 1.5 subject to the following lemma.

Lemma 4.1 *For any $n_2 \leq L^2$, the configurations of minimal energy with n_2 particles of type 2 belong to $\mathcal{V}_{\star, n_2}^{4n_2}$, i.e., are 2-tiled configurations.*

The proof of this lemma is given in Section 4.2.

4.1 Proof of Theorem 1.5 subject to Lemma 4.1

Proof. For $\mathcal{Y} \subset \mathcal{X}$, define the *external boundary* of \mathcal{Y} by $\partial\mathcal{Y} = \{\eta \in \mathcal{X} \setminus \mathcal{Y} : \exists \eta' \in \mathcal{Y}, \eta \leftrightarrow \eta'\}$ and the *bottom* of \mathcal{Y} by $\mathcal{F}(\mathcal{Y}) = \arg \min_{\eta \in \mathcal{Y}} H(\eta)$. According to Manzo, Nardi, Olivieri and Scoppola [5], Section 4.2, $\Phi(\square, \boxplus) = \min_{\eta \in \partial\mathcal{B}} H(\eta)$ for $\mathcal{B} \subset \mathcal{X}$ any (!) set with the following properties:

- (I) \mathcal{B} is connected via allowed moves, $\square \in \mathcal{B}$ and $\boxplus \notin \mathcal{B}$.
- (II) There is a path $\omega^* : \square \rightarrow \boxplus$ such that $\{\arg \max_{\eta \in \omega^*} H(\eta)\} \cap \mathcal{F}(\partial\mathcal{B}) \neq \emptyset$.

Thus, our task is to find such a \mathcal{B} and compute the lowest energy of $\partial\mathcal{B}$.

For (I), choose \mathcal{B} to be the set of all configurations η such that $n_2(\eta) \leq \ell^*(\ell^* - 1) + 1$. Clearly this set is connected, contains \square and does not contain \boxplus .

For (II), choose ω^* as follows. A particle of type 2 is brought inside Λ ($\Delta H = \Delta_2$), moved to the origin and is saturated by four times bringing a particle of type 1 ($\Delta H = \Delta_1$) and attaching it to the particle of type 2 ($\Delta H = -U$). After this first 2-tile has been completed, ω^* follows a sequence of increasing 2-tiled dual quasi-squares. The passage from one quasi-square to the next is obtained by *adding* a 12-bar to one of the longest sides, as follows. First a particle of type 2 is brought inside Λ ($\Delta H = \Delta_2$) and is attached to one of the longest sides of the quasi-square ($\Delta H = -2U$). Next, twice a particle of type 1 is brought inside the box ($\Delta H = \Delta_1$) and is attached to the (not yet saturated) particle of type 2 ($\Delta H = -U$) in order to complete a 2-tiled protuberance. Finally, the 12-bar is completed by bringing a particle of type 2 inside Λ ($\Delta H = \Delta_2$), moving it to a concave corner ($\Delta H = -3U$), and saturating it with a particle of type 1 ($\Delta H = \Delta_1$, respectively, $\Delta H = -U$). It is obvious that ω^* eventually hits \boxplus . The path ω^* is referred to as the *reference path for the nucleation*.

Call η^* the configuration in ω^* consisting of an $\ell^* \times (\ell^* - 1)$ quasi-square, a 2-tiled protuberance attached to one of its longest sides, and a free particle of type 2 (see Fig. 11; there are many choices for ω^* depending on where the 2-tiled protuberances are added; all these choices are equivalent. Note that, in the notation of Lemma 3.2, $\eta^* = \eta^{\ell^* - 1, 1, 1} + \text{fp}[2]$, where $\text{fp}[2]$ denotes the addition of a free particle of type 2. Observe that:

- (a) ω^* exits \mathcal{B} via the configuration η^* ;
- (b) $\eta^* \in \mathcal{F}(\partial\mathcal{B})$;

(c) $\eta^* \in \{\arg \max_{\eta \in \omega^*} H(\eta)\}$.

Observation (a) is obvious, while (b) follows from Lemmas 3.1 and 4.1. To see (c), note the following: (1) The total energy difference obtained by adding a 12-bar of length ℓ on the side of a 2-tiled cluster is $\Delta H(\text{adding a 12-bar}) = \Delta_1 - \varepsilon\ell$, which changes sign at $\ell = \ell^*$ (recall (3.7)); (2) The configurations of maximal energy in a sequence of growing quasi-squares are those where a free particle of type 2 enters the box after the 2-tiled protuberance has been completed. Thus, within energy barrier $2\Delta_1 + 2\Delta_2 - 4U = 4U - \varepsilon$ the 12-bar is completed downwards in energy. This means that, after configuration η^* is hit, the dynamics can reach the 2-tiled dual square of $\ell^* \times \ell^*$ while staying below the energy level $H(\eta^*)$. Since all 2-tiled dual quasi-squares larger than $\ell^* \times (\ell^* - 1)$ have an energy smaller than that of the 2-tiled dual quasi-square $\ell^* \times (\ell^* - 1)$ itself, the path ω^* does not again reach the energy level $H(\eta^*)$.

Because of (a-c), we have $\Phi(\square, \boxplus) = H(\eta^*)$. To complete the proof, use Lemma 3.2 to compute

$$H(\eta^*) = H(\eta^{\ell^* - 1, 1, 1} + \text{fp}[2]) = -\varepsilon[\ell^*(\ell^* - 1) + 1] + \Delta_1(2\ell^* + 1) + \Delta_2. \quad (4.1)$$

■

■

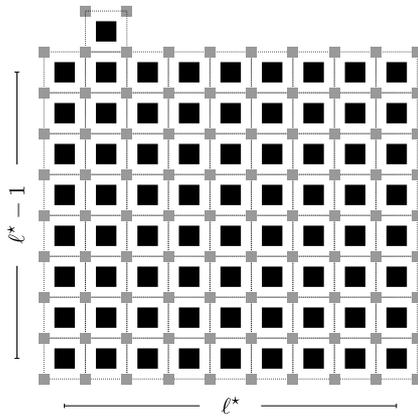


Figure 11: A critical configuration η^* . This is the dual version of the critical droplet in Fig. 4.

4.2 Proof of Lemma 4.1

The proof of Lemma 4.1 is carried out in two steps. In Section 4.2.1 we show that the claim holds for single-cluster configurations with a fixed number of particles of type 2. In Section 4.2.2 we extend the claim to general configurations with a fixed number of particles of type 2.

4.2.1 Single clusters of minimal energy are 2-tiled clusters

Lemma 4.2 *For any single-cluster configuration $\eta \in \mathcal{V}_{\star, n_2} \setminus \mathcal{V}_{\star, n_2}^{A n_2}$ there exists a configuration $\tilde{\eta} \in \mathcal{V}_{\star, n_2}^{A n_2}$ such that $H(\tilde{\eta}) < H(\eta)$.*

Proof. Pick any $\eta \in \mathcal{V}_{\star, n_2} \setminus \mathcal{V}_{\star, n_2}^{A n_2}$. Every neighboring site of a particle of type 2 in the cluster is either empty or occupied by a particle of type 1, and there is at least one non-saturated particle of type 2. Since η consists of a single cluster, $\tilde{\eta}$ can be constructed in the following way:

- $\tilde{\eta}(i) = \eta(i)$ for all $i \in \text{supp}(\eta)$.
- $\tilde{\eta}(j) = 1$ for all $j \notin \text{supp}(\eta)$ such that there exists an $i \sim j$ with $\eta(i) = 2$.

Since

$$\begin{aligned} H(\eta) &= \Delta_1 n_1(\eta) + \Delta_2 n_2(\eta) - UB(\eta), \\ H(\tilde{\eta}) &= \Delta_1 n_1(\tilde{\eta}) + \Delta_2 n_2(\tilde{\eta}) - UB(\tilde{\eta}), \end{aligned} \quad (4.2)$$

and $n_2(\eta) = n_2(\tilde{\eta})$, we have

$$H(\tilde{\eta}) - H(\eta) = \Delta_1 [n_1(\tilde{\eta}) - n_1(\eta)] - U[B(\tilde{\eta}) - B(\eta)]. \quad (4.3)$$

By construction, $B(\tilde{\eta}) - B(\eta) \geq n_1(\tilde{\eta}) - n_1(\eta) > 0$. Since $0 < \Delta_1 < U$ (recall (1.12)), it follows from (4.3) that $H(\tilde{\eta}) < H(\eta)$. \blacksquare

4.2.2 Configurations of minimal energy with fixed number of particles of type 2

Lemma 4.3 *For any n_2 and any configuration $\eta \in \mathcal{V}_{*,n_2}$ consisting of at least two clusters, any configuration η^* such that η^* is a single cluster, $\eta^* \in \mathcal{V}_{*,n_2}^{4n_2}$ and η^* is a standard configuration satisfies $H(\eta^*) < H(\eta)$.*

Proof. Let $\eta \in \mathcal{V}_{*,n_2}$ be a configuration consisting of $k > 1$ clusters, labeled c_1, \dots, c_k . Let $\eta^{n_2(c_i)}$ denote any standard configuration with $n_2(c_i)$ particles of type 2. By Lemmas 3.1 and 4.2, we have

$$H(\eta) = \sum_{i=1}^k H(c_i) \geq \sum_{i=1}^k H(\eta^{n_2(c_i)}). \quad (4.4)$$

By Lemma 2.3, we have (recall (1.14))

$$\begin{aligned} \sum_{i=1}^k H(\eta^{n_2(c_i)}) &= \sum_{i=1}^k [\Delta_1 n_1(\eta^{n_2(c_i)}) + \Delta_2 n_2(\eta^{n_2(c_i)}) - UB(\eta^{n_2(c_i)})] \\ &= \sum_{i=1}^k [\Delta_1 \{n_2(\eta^{n_2(c_i)}) + \frac{1}{4}\mathcal{T}(\eta^{n_2(c_i)})\} + \Delta_2 n_2(\eta^{n_2(c_i)}) - U4n_2(\eta^{n_2(c_i)})] \\ &= \sum_{i=1}^k [-\varepsilon n_2(\eta^{n_2(c_i)}) + \frac{1}{4}\Delta_1 \mathcal{T}(\eta^{n_2(c_i)})]. \end{aligned} \quad (4.5)$$

But from Lemma 2.2 it follows that

$$\sum_{i=1}^k \mathcal{T}(\eta^{n_2(c_i)}) > \mathcal{T}(\eta^{\sum_{i=1}^k n_2(c_i)}), \quad (4.6)$$

where $\eta^{\sum_{i=1}^k n_2(c_i)}$ denotes any standard configuration with $\sum_{i=1}^k n_2(c_i) = n_2(\eta)$ particles of type 2. Combining (4.4–4.6), we arrive at

$$H(\eta) > -\varepsilon n_2(\eta) + \frac{1}{4}\Delta_1 \mathcal{T}(\eta^{n_2(\eta)}) = H(\eta^{n_2(\eta)}). \quad (4.7)$$

\blacksquare

5 Proof of Theorem 1.4: upper bound on V_η for $\eta \notin \{\square, \boxplus\}$

In this section we show that for any configuration $\eta \notin \{\square, \boxplus\}$ it is possible to find a path $\omega: \eta \rightarrow \eta'$ with $\eta' \in \{\square, \boxplus\}$ such that $\max_{\xi \in \omega} H(\xi) \leq H(\eta) + V^*$ with $V^* \leq 10U - \Delta_1$ and $\eta' \in I_\eta$. By Definition 1.1(c–e), this implies that $V_\eta \leq V^*$ for all $\eta \notin \{\square, \boxplus\}$ and therefore settles Theorem 1.4.

Section 5.3 describes an *energy reduction algorithm* to find ω . Roughly, the idea is that if η contains only “subcritical clusters”, then these clusters can be removed one by one to reach \square , while if η contains

some “supercritical cluster”, then this cluster can be taken as a stepping stone to construct a path to \boxplus that goes via a sequence of increasing rectangles. In particular, the supercritical cluster is first extended to a 2-tiled rectangle touching the north-boundary of Λ , after that it is extended to a 2-tiled rectangle touching the west-boundary and the east-boundary of Λ , and finally it is extended to \boxplus .

To carry out this task, six *energy reduction mechanisms* are needed, which are introduced and explained in Section 5.2:

- Moving unit holes inside 2-tiled clusters (Section 5.2.1).
- Adding and removing 12-bars from lattice-connecting rectangles (Section 5.2.2).
- Changing bridges into 12-bars (Section 5.2.3).
- Maximally expanding 2-tiled rectangles (Section 5.2.4).
- Merging adjacent 2-tiled rectangles (Section 5.2.5).
- Removing subcritical clusters (Section 5.2.6).

Each of Sections 5.2.1–5.2.6 states a definition and a lemma, and uses these to prove a proposition about the relevant energy reduction mechanism. The six propositions thus obtained will be crucial for the energy reduction algorithm in Section 5.3.

In Section 5.1 we begin by defining beams and pillars, which are needed throughout Section 5.2.

5.1 Beams and pillars

Lemma 5.1 *Let η be a configuration containing a tile t that has at least three junction sites occupied by a particle of type 1. Then the configuration η' obtained from η by turning t into a 2-tile satisfies $H(\eta') \leq H(\eta)$.*

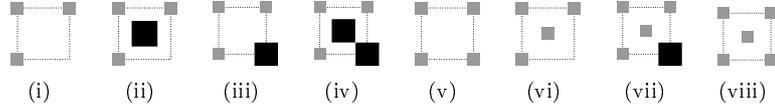


Figure 12: Possible tiles with at least three junction sites occupied by a particle of type 1.

Proof. W.l.o.g. we may assume that $\eta(t_a) = \eta(t_b) = \eta(t_d) = 1$, and that η' is the configuration in Fig. 6(d), i.e., $\eta'(t_a) = \eta'(t_b) = \eta'(t_c) = \eta'(t_d) = 1$, $\eta'(t_e) = 2$. The following eight cases are possible (see Fig. 12 and recall (1.12)):

- (i) $(\eta(t_c), \eta(t_e)) = (0, 0)$. One particle of type 1 and one particle of type 2 are added, and at least four new bonds are activated: $\Delta H \leq \Delta_1 + \Delta_2 - 4U < 0$.
- (ii) $(\eta(t_c), \eta(t_e)) = (0, 2)$. One particle of type 1 is added, and one new bond is activated: $\Delta H = \Delta_1 - U < 0$.
- (iii) $(\eta(t_c), \eta(t_e)) = (2, 0)$. One particle of type 2 is moved to another site without deactivating any bonds, after which case (ii) applies.
- (iv) $(\eta(t_c), \eta(t_e)) = (2, 2)$. One particle of type 2 with at most three active bonds is replaced by one particle of type 1 with at least one active bond: $\Delta H \leq \Delta_1 - \Delta_2 + 2U < 0$.
- (v) $(\eta(t_c), \eta(t_e)) = (1, 0)$. One particle of type 2 is added, and four new bonds are activated: $\Delta H = \Delta_2 - 4U < 0$.

- (vi) $(\eta(t_c), \eta(t_e)) = (0, 1)$. One particle of type 1 is moved to another site without deactivating any active bond, one particle of type 2 is added, and at least four new bonds are activated: $\Delta H \leq \Delta_2 - 4U < 0$.
- (vii) $(\eta(t_c), \eta(t_e)) = (2, 1)$. Two particles are exchanged without deactivating any bonds: $\Delta H \leq 0$.
- (viii) $(\eta(t_c), \eta(t_e)) = (1, 1)$. One particle of type 1 is replaced by a particle of type 2, and four new bonds are activated: $\Delta H = \Delta_2 - \Delta_1 - 4U < 0$.

■

Definition 5.2 A beam of length ℓ is a row (or column) of $\ell + 1$ particles of type 1 at dual distance 1 of each other. A pillar is a particle of type 1 at dual distance 1 of the beam not located at one of the two ends of the beam. The particle in the beam sitting next to the pillar divides the beam into two sections. The lengths of these two sections are ≥ 0 and sum up to ℓ . The support of a pillared beam is the union of all the tile supports. The support consists of three rows (or columns) of sites – an upper, middle and lower row (or column) – which are referred to as roof, center and basement (see Fig. 13).

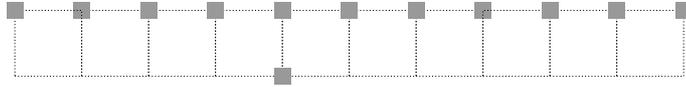


Figure 13: A south-pillared horizontal beam of length 10 with a west-section of length 4 and an east-section of length 6.

Note that a beam can have more than one pillar. Lemma 5.1 implies the following.

Corollary 5.3 Let η be a configuration containing a pillared beam \tilde{b} such that $\text{supp}(\tilde{b})$ is not 2-tiled. Then the configuration η' obtained from η by 2-tiling $\text{supp}(\tilde{b})$ satisfies $H(\eta') \leq H(\eta)$.

5.2 Six energy reduction mechanisms

5.2.1 Moving unit holes inside 2-tiled clusters

In this section we show how a unit hole can move inside a 2-tiled cluster. In particular, we show that such motion is possible within an energy barrier $6U$ by changing the configuration only locally.

Definition 5.4 A set of sites S inside Λ obtained from a 4×4 square after removing the four corner sites is called a slot.

Given a slot S , we assign a label to each of the 12 sites in S as in Fig. 14 (a): first clockwise in the center of S and then clockwise on the boundary of S . We call the pairs (S_1, S_3) and (S_2, S_4) slot-conjugate sites.

Lemma 5.5 Let S be a slot, and let η_0 be any configuration such that all particles in S have the same parity. W.l.o.g. this parity may be taken to be even, so that $\eta(S_1) = 0$ and $\eta(S_3) = 2$. Let η_1 be the configuration obtained from η by interchanging the states of S_1 and S_3 . Then $H(\eta_0) = H(\eta_1)$, and there exists a path $\omega: \eta_0 \rightarrow \eta_1$ that never exceeds the energy level $H(\eta_0) + 6U$.

Proof. W.l.o.g. we take η_0 as in Fig. 14(b-c). Let $a \rightarrow b$ denote the motion of a particle from site a to site b . For the path ω we choose the following sequence of moves: $S_4 \rightarrow S_1$; $S_3 \rightarrow S_4$; $S_2 \rightarrow S_3$; $S_1 \rightarrow S_2$; $S_4 \rightarrow S_1$; $S_3 \rightarrow S_4$. The first three moves and the second three moves each are a rotation by $\frac{\pi}{2}$ of the subconfiguration at the sites S_1, S_2, S_3, S_4 . Note that all configurations in ω have the same number of particles of each type and hence the changes in energy only depend on the change in the

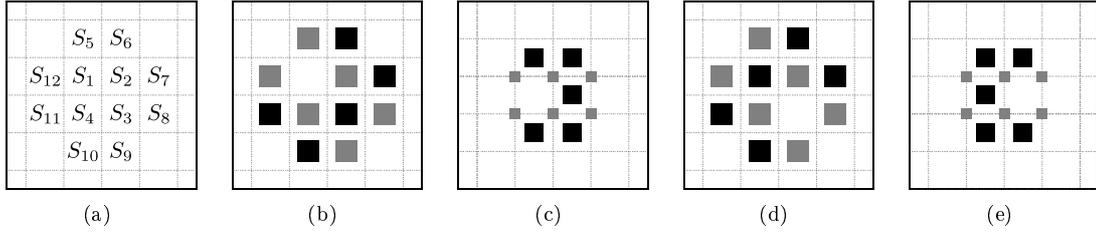


Figure 14: (a) labelling of the sites in the slot (standard representation); (b) example of η_0 in the slot (standard representation); (c) example of η_0 in the slot (dual representation). (d) η_1 in the slot (standard representation); (e) of η_1 in the slot (dual representation).

number of active bonds. Let M_{RF} be the loss of the number of active bonds between the rotating particles and the fixed particles, and M_R the loss of the number of active bonds between the rotating particles. We must show that $M_{RF} + M_R \leq 6$ during the six moves. To that end, we first observe that $M_{RF} \leq 6$, since the total number of active bonds between the rotating particles and the fixed particles is at most 6 (see Fig. 14(b)), and that $M_{RF} = 6$ only after the first three moves are completed, i.e., when the configuration is such that all the rotating particles have a different parity with respect to the parity they had in configuration η_0 (recall that particles with different parity cannot share a bond). Next we observe that, by the choice of ω , the value of M_R can only be 0 or 1, and that $M_R = 0$ after the first three moves are completed. ■

Lemma 5.5 implies the following.

Proposition 5.6 *Let η be a 2-tiled configuration with a unit hole. Then the configuration η' obtained from η by moving the unit hole elsewhere satisfies $H(\eta') = H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + 6U$.*

A possible $6U$ -path for a unit hole inside a 2-tiled cluster is given in Fig. 15. This path is obtained through an iteration of local moves as explained in Fig. 14.

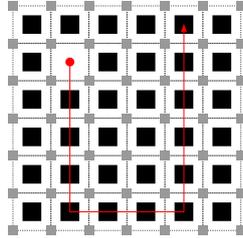


Figure 15: Motion of a unit hole inside a 2-tiled cluster.

5.2.2 Adding and removing 12-bars from lattice-connecting rectangles

Lemma 5.7 *Let η be a configuration consisting of a single 2-tiled lattice-connecting rectangle. Then the configuration η' obtained from η by, respectively,*

1. adding a 12-bar of length $\ell \geq \ell^*$,
2. adding a 12-bar of length $\ell < \ell^*$,
3. removing a 12-bar of length $\ell \geq \ell^*$,
4. removing a 12-bar of length $\ell < \ell^*$,

satisfies, respectively,

1. $H(\eta') < H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + 2\Delta_1 + 2\Delta_2 - 4U$,
2. $H(\eta') > H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + 2\Delta_1 + 2\Delta_2 - 4U$,
3. $H(\eta') > H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + (\ell - 2)\varepsilon + 4U - \Delta_1$,
4. $H(\eta') < H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + (\ell - 2)\varepsilon + 4U - \Delta_1$.

Proof. Recall the computations in Sections 3.1 and 4.1.

Adding a 12-bar. Adding a 12-bar of length ℓ on a lattice-connecting side of a 2-tiled rectangle (i.e., a side such that all the particles of type 1 on that side are lattice-connecting) can be done in two steps: (i) initiate the 12-bar by adding a 2-tiled protuberance (see Fig. 16); (ii) complete the 12-bar by adding a 2-tile (in a “corner”) $\ell - 1$ times (see Fig. 17). This can be achieved within energy barrier $\Delta H = 2\Delta_1 + 2\Delta_2 - 4U$ by following the same moves as the reference path ω^* described in Section 4.1. The energy difference due to the extra 12-bar of length ℓ is $\Delta H(\ell) = \Delta_1 - \ell\varepsilon$, which changes sign at $\ell = \ell^*$.

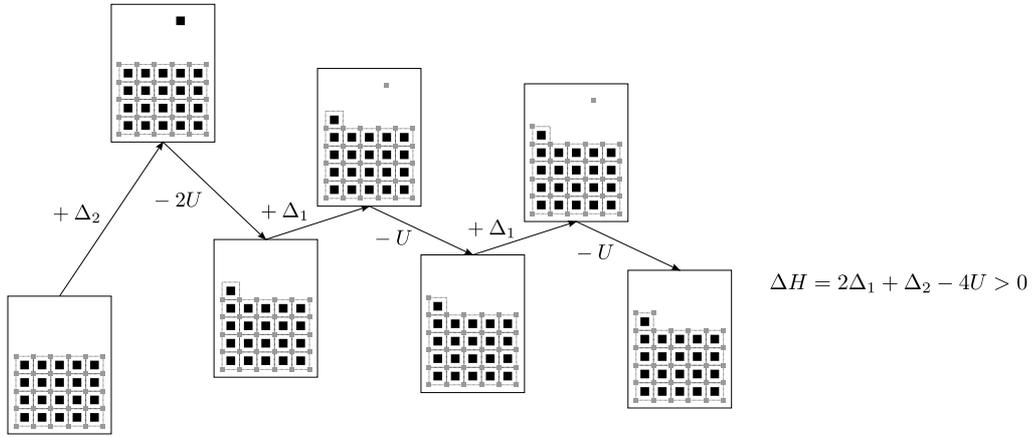


Figure 16: A 2-tiled protuberance is added to a side of a dual rectangle within energy barrier Δ_2 .

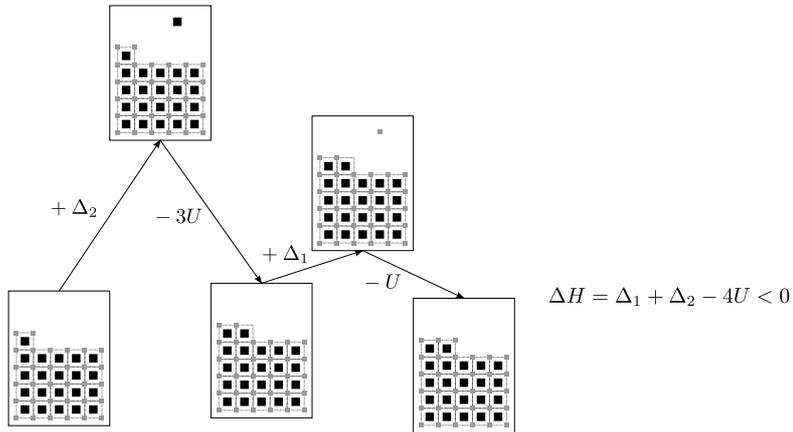


Figure 17: A 2-tile is added in a corner between 2-tiles within a energy barrier Δ_2 .

Removing a 12-bar. Removing a 12-bar of length ℓ from a lattice-connecting rectangle can be done by following the reverse of the path used to add a 12-bar: (i) remove $\ell - 1$ times a 2-tile from a bar; (ii) remove the last 2-tiled protuberance. This can be achieved within energy barrier

$\Delta H(\ell) = (\ell - 2)\varepsilon + 4U - \Delta_1$. If the cluster consists of one 12-bar only, then the path just described leaves $\ell + 1$ free particles of type 1 inside Λ , which can be removed (free of energy cost) afterwards. ■

We use Lemma 5.7 to build a *northern rectangle* on top of a 12-bar as follows.

Definition 5.8 Let b denote the vertical coordinate of the sites lying on the north-side of $\partial^-\Lambda^-$. For a given 2-tiled rectangle r in Λ^- , let b_r denote the vertical coordinate of the northern-most particles of type 1 in r . Then r is said to be touching the north-side of $\partial^-\Lambda^-$ if $b_r = b$ or $b_r = b - \frac{1}{2}$.

In words, a 2-tiled rectangle is said to be touching the north-side of $\partial^-\Lambda^-$ if it is not possible to add a 12-bar on the north-side within Λ^- . Rectangles touching the south-, east- or west-side of Λ^- are defined similarly.

Let \bar{b} be a horizontal 12-bar of length ℓ , i.e., a 2-tiled $\ell \times 1$ rectangle. Suppose that all sites above \bar{b} are vacant. Then it is possible to successively add horizontal 12-bars, say m in total, on top of \bar{b} until the north side of the rectangle grown in this way touches the north-side of Λ^- . The 2-tiled rectangle with $m + 1$ rows and ℓ columns such that \bar{b} is its lower-most horizontal 12-bar is denoted by $\square(\bar{b})$ and is called the northern rectangle of \bar{b} .

Lemma 5.7 implies the following.

Proposition 5.9 Let η be a configuration containing a horizontal 12-bar \bar{b} of length $\ell \geq \ell^*$. Then the configuration η' obtained from η by building $\square(\bar{b})$ satisfies $H(\eta') < H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + 2\Delta_1 + 2\Delta_2 - 4U$.

5.2.3 Changing bridges into 12-bars

Definition 5.10 A (south-)bridge b consists of a beam \tilde{b} and two (south-)pillars at the outer-most sites of the (south-)basement of \tilde{b} . The (south-)support of b coincides with the (south-)support of \tilde{b} . If each of the central sites of the tiles of the (south-)support of the bridge is occupied by a particle of type 2, then the bridge is said to be stable (see Fig. 18).

Clearly, a 12-bar is a stable bridge. North-, east- and west-bridges are defined in a similar way.

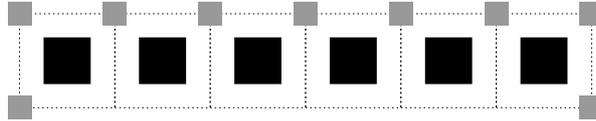


Figure 18: A stable bridge of length 6.

Given a bridge b , let \bar{b} denote the 12-bar obtained by 2-tiling b . Lemma 5.1 implies the following.

Lemma 5.11 Let η be a configuration containing a bridge b whose support is not 2-tiled. Then the configuration η' obtained from η by changing b to \bar{b} satisfies $H(\eta') < H(\eta)$.

Lemma 5.11 leads us to the following.

Proposition 5.12 Let η be a configuration containing a (south-)bridge b whose (south-)support is not 2-tiled such that the particles of its beam are lattice-connecting. Then the configuration η' obtained from η by 2-tiling $\text{supp}(b)$ satisfies $H(\eta') < H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + 4U + \Delta_1$.

Proof. Let the (south-)bridge b have length ℓ . Label the $\ell + 1$ sites of its (south-)basement as s_0, s_1, \dots, s_ℓ , from the left to the right. In order to show that $\text{supp}(b)$ can be 2-tiled within energy barrier $4U + \Delta_1$, it is enough to show that within the same energy barrier a particle of type 1 can be brought to a site of the basement of b (from the left) that is empty or is occupied by a particle of type

2. W.l.o.g. s_1 may be assumed to be such a site. The configuration thus obtained has an energy that is at most the energy of the original configuration (see Lemma 5.1). The claim follows by noting that the particles of type 1 at the extremal sites s_1 and s_ℓ are the two pillars of a (south-)bridge of length $\ell - 1$ whose basement consists of the sites s_1, s_2, \dots, s_ℓ .

It remains to show how a particle of type 1 can be brought to site s_1 . Label the site north-west of s_1 by v_1 , and the site north-east of v_1 by v_2 . Two cases need to be distinguished:

(1) If $\eta(s_1) = 0$, then, by the same argument as in the proof of Lemma 5.5, it is easy to show that the particle of type 1 at v_2 can be moved to s_1 (to obtain a configuration $\bar{\eta}$ with $H(\bar{\eta}) \leq H(\eta)$) without exceeding energy level $H(\eta) + 4U$. The configuration η' is reached within an energy barrier Δ_1 by bringing a particle of type 1 inside Λ and moving it to v_2 .

(2) If $\eta(s_1) = 2$, then consider the following path. First detach ($\Delta H = 2U$) and remove ($\Delta H = -\Delta_1$) the particle of type 1 at v_2 , and afterwards detach ($\Delta H = 2U$) and remove ($\Delta H = -\Delta_2$) the particle of type 2 at v_3 . Next, move the particle of type 2 at site s_1 to site v_1 ($\Delta H \leq 0$; this particle has at most 2 active bonds when it sits at s_1), and finally bring a particle of type 1 ($\Delta H = \Delta_1$) to site v_2 ($\Delta H = -2U$). Call this configuration $\bar{\eta}$. Note that $H(\bar{\eta}) < H(\eta)$, since effectively a particle of type 2 with at most two active bonds has been removed, and $\Phi(\eta, \eta') = H(\eta) + 4U + \Delta_1$. Finally, observe that η' is the same configuration as η in Case (1). ■

5.2.4 Maximally expanding 2-tiled rectangles

The mechanism presented in this section, which is called *north maximal expansion* of a 2-tiled rectangle, is such that it can be applied to a 2-tiled rectangle whose north-side is lattice-connecting (even though this condition is not restrictive). South, east and west maximal expansion of a 2-tiled cluster are analogous.

Definition 5.13 *The north maximal expansion comes in two phases: a growing phase and a smoothing phase.*

(i) *The growing phase consists of the following three steps repeated cyclically:*

1. *If the particles of type 1 on the south-side of the rectangle, either at the beginning or obtained after step 3, constitute a south-pillared beam \tilde{b}_s , then change $\text{supp}(\tilde{b}_s)$ into a 12-bar.*
2. *If the particles of type 1 on the east-side of the rectangle, obtained after step 1, constitute an east-pillared beam \tilde{b}_e , then change $\text{supp}(\tilde{b}_e)$ into a 12-bar.*
3. *If the particles of type 1 on the west-side of the rectangle, obtained after step 2, constitute a west-pillared beam \tilde{b}_w , then change $\text{supp}(\tilde{b}_w)$ into a 12-bar.*

The growing phase ends after three consecutive steps leave the configuration unchanged.

(ii) *The smoothing phase consists of removing all the particles of type 2 that are adjacent to the ones on the sides of the rectangle that is built during the growing phase. Note that these particles have at most two active bonds (otherwise it would be possible to identify another pillared beam), and therefore removal of these particles lowers the energy.*

The outcome of the north maximal expansion (see Fig. 19) of a 2-tiled rectangle is again a 2-tiled rectangle, containing the old rectangle and such that the northern-most 12-bar of the new rectangle has the same vertical coordinate.

Given a 2-tiled rectangle r , let $\mathcal{R}^\top(r)$ denote the north maximal expansion of r . Corollary 5.3 implies the following.

Lemma 5.14 *Let η be a configuration containing a 2-tiled rectangle. Then the configuration η' obtained from η via (north) maximal expansion of this 2-tiled rectangle satisfies then $H(\eta') \leq H(\eta)$.*

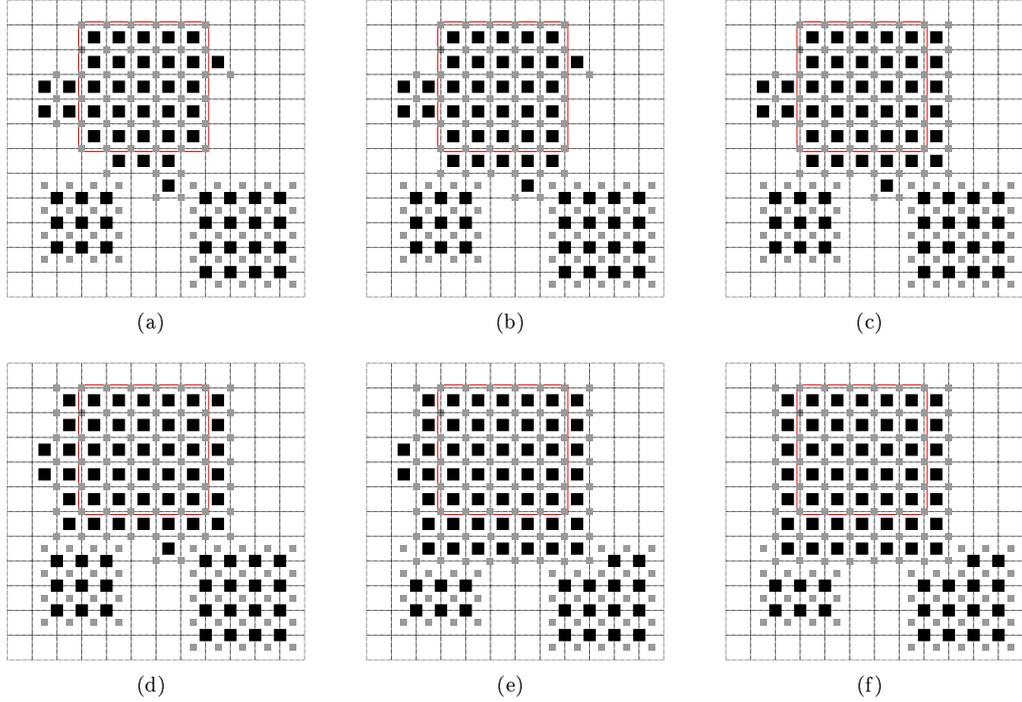


Figure 19: Example of north maximal expansion of a 2-tiled rectangle. The outcome of the steps of the growing phase are represented in pictures (b–e), while the outcome of the smoothing phase is represented in picture (f).

Lemma 5.14 leads us to the following.

Proposition 5.15 *Let η be a configuration containing a 2-tiled rectangle r whose north-side is lattice-connecting. Then the configuration η' obtained from η after replacing r by $\mathcal{R}^\top(r)$ satisfies $H(\eta') \leq H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + 10U - \Delta_1$.*

Proof. If $\mathcal{R}^\top(r) = r$, then there is nothing to prove. Therefore suppose that r is such that one its sides is a pillared beam. W.l.o.g. we may assume that the south-side of r is a beam \tilde{b} with a south-pillar. We must show that the south-support of \tilde{b} can be turned into a 12-bar within energy barrier $10U - \Delta_1$.

Since $\text{supp}(\tilde{b})$ is not a 12-bar, a pillar can be chosen in such a way that at least one of the 2-tiles of the support the pillar belongs to (i.e., the first tile of each section of the support, counting from the pillar) is not a 2-tile. W.l.o.g. we let this tile be the first tile of the right-section and call it t . Let v denote the tile adjacent to the right site of v . In the following, the term *superficial* refers to tiles that are in the top tile-bar of the rectangle. In analogy with the proof of Lemma 5.1, several cases need to be considered (we stick to the order in Fig. 12).

- (i) $(\eta(t_e), \eta(t_e)) = (0, 0)$. A particle of type 2 has to be brought to site t_e and a particle of type 1 to site t_e . First bring a particle of type 2 to site t_e , to reach a configuration $\hat{\eta}$, and then proceed as in Case (ii). As we will see in Case (ii), since $H(\hat{\eta}) = H(\eta) - 3U + \Delta_2$, the second part of the path can be completed without exceeding energy level $H(\eta) + 6U + \Delta_2$. To reach configuration $\hat{\eta}$, move the particle of type 2 of the 2-tile above t to site t_e to reach a configuration called η' . This can be done without exceeding energy level $H(\eta) + 6U$. Note that $H(\eta') = H(\eta) + U$. The unit hole that has been created at the central site of the tile above t has to be filled. This can be done (see Lemma 5.5) by first moving the unit hole until it becomes superficial (configuration $\tilde{\eta}$ with energy $H(\tilde{\eta}) = H(\eta')$) without exceeding energy level $H(\eta') + 6U$, and then filling this unit hole with a particle of type 2 within energy level $H(\eta') + U - \Delta_1 + \Delta_2 = H(\eta) + 2U - \Delta_1 + \Delta_2$. Thus, η' can be reached without exceeding energy barrier $6U + \Delta_2$.

- (ii) $(\eta(t_c), \eta(t_e)) = (0, 2)$. A particle of type 1 has to be brought to site t_c . Depending on the state of site v_e , there are three cases.
- (a) Site v_e is occupied by a particle of type 2. Move the particle of type 1 at site t_b to site t_c , to reach a configuration η' with energy $H(\eta') \leq H(\eta) + 2U$ within an energy barrier of $6U$. The vacancy at site t_b can be moved (again by Lemma 5.5) to the north-side of the rectangle within energy barrier $6U$, to reach a configuration $\hat{\eta}$ with $H(\hat{\eta}) \leq H(\eta)$, and then filled with an extra particle of type 1. Thus, η' can be reached without exceeding energy level $H(\eta) + 8U$.
 - (b) Site v_e is empty. Move the particle of type 1 at site t_b to site v_e ($\Delta H \leq 3U$), and then to site t_d ($\Delta H = 0$). Call this configuration η' , and note that $H(\eta') \leq H(\eta) + 2U$. Arguing as above, we see that the vacancy at site t_b can be filled without exceeding the energy level $H(\eta) + 9U$.
 - (c) Site v_e is occupied by a particle of type 1. Observe that the particle of type 1 at t_b has $k \leq 3$ active bonds and the particle of type 2 at v_e has $m \leq 2$ active bonds. It is possible to move the particle at site v_e to site t_c ($\Delta H = (m - k)U$), and then the particle at site t_b to site v_e ($\Delta H = (k - m)U$). The configuration η' , reached within energy barrier $(k - m)U$, has energy $H(\eta') \leq H(\eta) + kU$. Again, the vacancy at site t_b has to be filled with a particle of type 1. This can be done without exceeding the energy level $H(\eta) + (6 + k)U \leq H(\eta) + 9U$.
- (iii) $(\eta(t_c), \eta(t_e)) = (2, 0)$. The particle of type 2 at site t_c is moved to site t_e without increasing the energy. Then argue as in Case (ii).
- (iv) $(\eta(t_c), \eta(t_e)) = (2, 2)$. The particle of type 2 at site t_c has to be replaced by a particle of type 1. Remove the particle of type 2 at t_e . To do this, first create a superficial unit hole (which can be done within energy barrier $4U - \Delta_1$ by creating a hole in a corner tile of the rectangle) and move this vacancy to site t_e . By Lemma 5.5, this can be achieved without exceeding energy level $H(\eta_0) + 10U - \Delta_2$. Then move the particle of type 2 at site t_c to site t_e ($\Delta H \leq 0$). Call η' the configuration that is reached in this way. Note that $H(\eta') \leq H(\eta) - \Delta_2 + 3U$. To bring a particle of type 1 to site t_e , argue as in Case (ii), to arrive at $H(\hat{\eta}) \leq H(\eta) + 12U - \Delta_2$.
- (v) $(\eta(t_c), \eta(t_e)) = (1, 0)$. A particle of type 2 has to be brought to site t_e . Move the unit hole at t_e to the top tile-bar of the rectangle. This does not change the energy of the configuration and can be done within energy barrier $6U$ by Proposition 5.6. The task reduces to filling a superficial unit hole on the surface of the cluster with a particle of type 2. This can be achieved within energy barrier $U + \Delta_2 - \Delta_1$. Therefore the maximal energy level reached in this case is $H(\eta) + 6U$.
- (vi) $(\eta(t_c), \eta(t_e)) = (0, 1)$. Move the particle of type 2 from site t_e to site t_c . This move does not increase the energy of the configuration. Then proceed as in Case (v).
- (vii) $(\eta(t_c), \eta(t_e)) = (2, 1)$. The occupation numbers of sites t_c and t_e have to be exchanged. To do this, first remove the particle of type 1 at site t_b to obtain a configuration η' with energy $H(\eta') \leq H(\eta) + 3U$ without exceeding the energy level $H(\eta) + 10U - \Delta_1$ (again use Lemma 5.5). Move the particle of type 1 from t_e to t_b ($\Delta H < 0$) and the particle of type 2 from t_c to t_e ($\Delta H = 0$). Call $\hat{\eta}$ the configuration that is reached in this way. Note that $H(\hat{\eta}) \leq H(\eta) + U - \Delta_1$. Proceed as in Case (ii) to conclude within energy barrier of $10U - \Delta_1$.
- (viii) $(\eta(t_c), \eta(t_e)) = (1, 1)$. The particle of type 1 at site t_e has to be replaced by a particle of type 2. This can be done as follows. First the particle of type 1 sitting a site t_b is removed. To achieve this, first remove a particle of type 1 at the north-side of the rectangle and then (use Lemma 5.5) move the vacancy to site t_b . The configuration that is reached, which we call η' , is such that $H(\eta') \leq H(\eta) + 3U - \Delta_1$. Next, move the particle of type 1 at t_e to site t_b ($\Delta H = 0$), to reach a configuration $\hat{\eta}$ whose energy is $H(\hat{\eta}) = H(\eta) - \Delta_1$. Finally, argue as in Case (v), to arrive at $H(\hat{\eta}) \leq H(\eta) + 3U - \Delta_1$.

Finally, note that (1.12) implies $\max\{6U + \Delta_2, 10U - \Delta_1, 12U - \Delta_2\} = 10U - \Delta_1$.

By Lemma 5.1, $H(\eta') \leq H(\eta)$, and therefore the same argument can be used to show that all the right-sections of the support can be 2-tiled within the same energy barrier. The left-section can be 2-tiled analogously.

To conclude, it remains to be shown how particles of type 2, possibly adjacent to one side of the rectangle, can be removed from Λ . Call t the tile associated with the particle p of type 2 that has to be removed (p sits at site t_e) and v the tile adjacent to t belonging to the rectangle. First bring a vacancy to site v_e within energy barrier $10U - \Delta_2$ (one way to achieve this has been described in Case (iv) above) and then move p to site v_e (see Lemma 5.5). \blacksquare

5.2.5 Merging adjacent 2-tiled rectangles

Definition 5.16 A 12-bar b_1 of length ℓ of a cluster c_1 is said to be adjacent to a 12-bar b_2 of length $m \leq \ell$ of a cluster c_2 if there exist m mutually disjoint pairs (q_1^i, q_2^i) of particles of type 1 with $q_1^i \in b_1$ and $q_2^i \in b_2$ such that $u(q_1^i) - u(q_2^i) = v$ with $\|v\| = \frac{1}{2}\sqrt{2}$ for $i = 1, \dots, m$. The vector v is called the offset of b_2 with respect to b_1 . The tiles in b_1 have a different parity than the tiles in b_2 . The particles $q_1^i \in b_1$, $i = 1, \dots, m$, are called the external particles of b_1 with respect to b_2 , and the particles $q_2^i \in b_2$, $i = 1, \dots, m$, are called the external particles of b_2 with respect to b_1 .

Proposition 5.17 Let η be a configuration that contains two adjacent 2-tiled rectangles. Then the configuration η' obtained by “merging” these two rectangles satisfies $H(\eta') = H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + 2U - \Delta_1$.

Proof. Given two adjacent bars b_1 and b_2 with offset $v = (v_1, v_2)$ in a configuration η , we want to define the sliding of b_2 onto b_1 along v . The resulting configuration η' is such that all the particles of type 2 originally in b_2 are slid by (v_1, v_2) with respect to their position in η , and all the external particles of type 1 of b_2 with respect to b_1 are slid by $(v_1, -v_2)$ when the two bars are horizontal and by $(-v_1, v_2)$ when the two bars are vertical. Via the sliding, the m 2-tiles in b_2 are turned into m 2-tiles with the same parity as the tiles in b_1 . It is easy to see that $H(\eta') = H(\eta)$, since neither the total number of active bonds of the configuration nor the number of particles of each type is changed.

To describe the sliding of a bar onto another bar along a vector v , we may assume w.l.o.g. that the two bars are vertical and that the vector v is equal to $(-\frac{1}{2}, -\frac{1}{2})$ (Fig. 20(a)). Start by moving the lower-most external particle of type 1 in b_2 over the vector $v' = (\frac{1}{2}, -\frac{1}{2})$ (Fig. 20(b)). This leads to an increase by U in energy. Then move the lower-most particle of type 2 over the vector v (Fig. 20(c)). Since the number of deactivated bonds is equal to the number of new bonds activated, this move does not change the energy. Proceed by moving over the vector v' the second particle of type 1 from the bottom of the bar (Fig. 20(d)). This also is a move that does not change the energy. Afterwards, the second particle of type 2 from the top is moved over the vector v (Fig. 20(e)). This sequence of moves proceeds iteratively (without a change in energy) until the m -th particle of type 2 has been moved over the vector v . Finally, the $(m+1)$ -st external particle of type 1 is moved over the vector v' (Fig. 20(f)). This move decreases the energy by U . Thus, U is the energy barrier that must be overcome in order to realize the sliding of a 12-bar onto another 12-bar over the vector v .

It is clear that, given a configuration η containing two 2-tiled rectangles c_1 (with vertical side length ℓ) and c_2 (with vertical side length $m \leq \ell$) with offset v , it is possible to reduce η to a configuration η' such that c_1 and c_2 are merged into of a single cluster by sliding one bar after another, without exceeding energy barrier $\Delta H = U$, provided the other clusters of η do not interfere with this procedure. Sliding the last bar of c_2 we get an excess of free particles of type 1, which can be removed from Λ , lowering the energy. In particular, the configuration η' obtained via the sliding of c_2 onto c_1 along v without exceeding energy level $H(\eta) + U$ has energy $H(\eta') = H(\eta) - (m+1)\Delta_1$, since the two configurations consist of the same number of 2-tiles, and η' contains $m+1$ particles of type 1 less than η . Moreover, $\Phi(\eta, \eta') = H(\eta) + U$.

In the argument above, the first move consisted of moving down-right a particle of type 1 of b_2 to an empty site (say, site i). If in configuration η site i is occupied by a particle of type 1, then

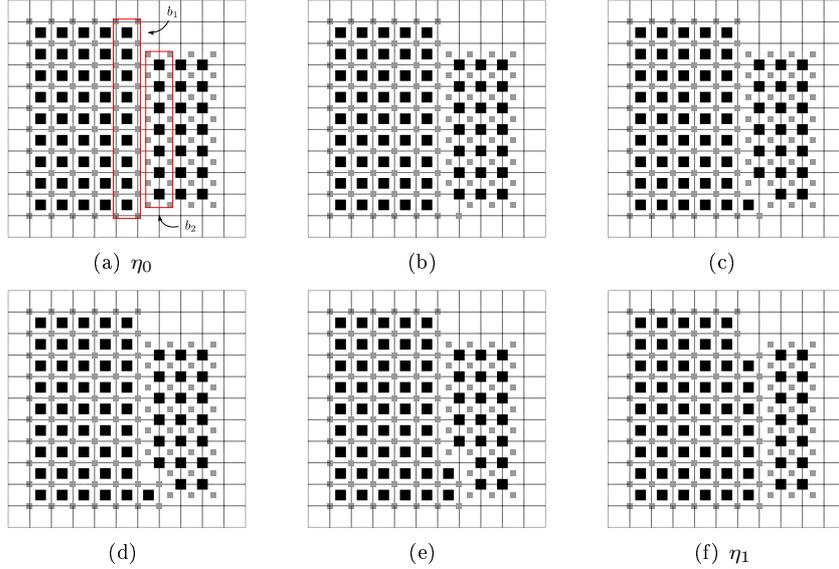


Figure 20: The sliding of b_2 onto b_1 .

the sliding of the vertical 12-bar can be realized by modifying the procedure as follows. First remove from the box the top-left particle of type 1 of b_2 sitting at site j to reach a configuration with energy $H(\eta) + U - \Delta_1$ (which can be done without exceeding energy level $H(\eta) + U$). Then move to j the particle of type 1 sitting at site $k = j + v = j + (-\frac{1}{2}, -\frac{1}{2})$ in η , which increases the energy up to level $H(\eta) + 2U - \Delta_1$. Then site k is filled with the particle of type 1 originally at site $k + (\frac{1}{2}, -\frac{1}{2})$ without an increase in energy. It is possible to continue in this way until the configuration obtained after the first step of the above case is reached. This configuration has energy $H(\eta) + U - \Delta_1$. Then proceed as in the above case until b_2 is slid onto b_1 . This leads to a configuration with energy $H(\eta) - \Delta_1 < H(\eta)$. In order to perform the (modified) sliding procedure, it is sufficient to assume that the north-side of rectangle c_2 is lattice-connecting. ■

5.2.6 Removing subcritical clusters

The *cleaning mechanism* defined in this section produces a configuration for which we have a certain control on the geometry of the constituent clusters. In particular, these clusters will be suitable for the application of the previous five energy reduction mechanisms. We begin by looking at pending dimers (see Fig. 21).

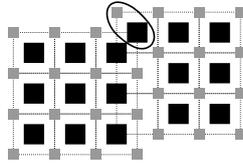


Figure 21: A pending dimer is the pair of particles circled in the picture.

Definition 5.18 A pending dimer consists of two adjacent particles of different type such that the particle of type 1 is lattice-connecting and has only one active bond and the particle of type 2 has at most three active bonds.

Proposition 5.19 Let η be a configuration containing pending dimers. Then there exists a configuration η' not containing pending dimers that satisfies $H(\eta') < H(\eta)$ and $\Phi(\eta, \eta') \leq H(\eta) + 3U + \Delta_2$.

Proof. If the particle of type 2 has at most two active bonds, then simply remove the pending dimer. This reduces the energy, since two bonds are deactivated and a particle of each type is removed from Λ ($\Delta H \leq 2U - \Delta_1 - \Delta_2 < 0$), and can be achieved within an energy barrier $2U - \Delta_1$ along the following path: first detach ($\Delta H = U$) and remove ($\Delta H = -\Delta_1$) the particle of type 1, then detach ($\Delta H \leq U$) and remove ($\Delta H = -\Delta_2$) the particle of type 2.

If the particle of type 2 has three active bonds we have two cases:

- (i) The fourth neighbor of the particle of type 2 of the pending dimer is empty. In this case η' is obtained by filling this empty site with a particle of type 1 in order to obtain a 2-tile, which lowers the energy since $\Delta_1 < U$. To do this, temporarily remove the pending dimer as described above. This leads to a configuration $\tilde{\eta}$ with energy $H(\tilde{\eta}) = H(\eta) + 3U - \Delta_1 - \Delta_2$ reached within energy barrier $3U - \Delta_1$. Then bring a particle of type 1 to the designated site ($\Delta H \leq \Delta_1$) and finally put back the dimer. The whole path is realized within energy barrier $3U + \Delta_2$.
- (ii) The fourth neighbor of the particle of type 2 is occupied by a particle of type 2. In this case η' is the configuration such that the dimer is removed and the site originally occupied by the particle of type 2 of the dimer is occupied by a particle of type 1. To obtain η' from η , remove the pending dimer (again, as above, within energy barrier $3U - \Delta_1$), to reach a configuration $\tilde{\eta}$ with energy $H(\tilde{\eta}) = H(\eta) + 3U - \Delta_1 - \Delta_2$, and bring a particle of type 1 within energy barrier Δ_1 . To conclude, observe that $H(\eta') = H(\eta) + 2U - \Delta_2 < H(\eta)$.

■

The cleaning mechanism works as follows:

1. Remove all the lattice-connecting free particles from the configuration.

After that repeat cyclically the following two steps:

2. Iteratively remove/transform all the lattice-connecting pending dimers.
3. Bring a particle of type 1 to any of the free sites adjacent to the lattice-connecting particles of type 2.

Repeat the cleaning mechanism until the configuration is not affected anymore. Each of the three steps can be performed within energy barrier $3U + \Delta_2$. Moreover, each step reduces the energy.

Lemma 5.20 *The outcome of the cleaning mechanism is either a configuration such that the first particle encountered while scanning Λ in the lexicographic order is a particle of type 1 belonging to a horizontal stable (south-)bridge, or the configuration \square .*

Proof. Call q the first particle of Λ in the lexicographic order. Recall that the dual coordinates of q are denoted by $u(q) = (u_1(q), u_2(q))$. Step 3 of the cleaning mechanism guarantees that q is a particle of type 1. The fact that q is the first particle in the lexicographic order implies that: (i) all the sites above $u(q)$ are empty; (ii) all the sites with the same vertical coordinate as q lying on the left of q are empty as well. As a consequence of (ii), all the sites on the left of q with vertical coordinate $u_2(q) - \frac{1}{2}$ are lattice-connecting and therefore cannot be occupied by a particle of type 2. Since q cannot be a free particle, the site with coordinates $(u_1(q) + \frac{1}{2}, u_2(q) - \frac{1}{2})$ must be occupied by a particle p of type 2. Let $s(p)$ be the longest sequence of tiles adjacent to $t(p)$ such that the central site is occupied by a particle of type 2. Obviously, p is the left-most particle of type 2 in $s(p)$. Call \tilde{p} the last particle of type 2 in $s(p)$ and \tilde{q} the particle of type 1 with coordinates $(u_1(p) + \frac{1}{2}, u_2(p) + \frac{1}{2})$. (Note that p and \tilde{p} may coincide.) All the sites on the north-side of $s(p)$ are lattice-connecting and hence are occupied by a particle of type 1. To conclude, observe that both p and \tilde{p} must be saturated, otherwise at least one of the pairs (q, p) and (\tilde{q}, \tilde{p}) constitutes a pending dimer. ■

5.3 Energy reduction of a general configuration: Proof of Theorem 1.4

Fix any $\eta \notin \{\square, \boxplus\}$. In this section we will give a general procedure, called *energy reduction algorithm*, that allows us to construct a path $\omega: \eta \rightarrow \eta_r$ with $\eta_r \in \{\square, \boxplus\}$ such that $\max_{\xi \in \omega} H(\xi) \leq H(\eta) + V^*$ with $V^* \leq 10U - \Delta_1$ and $H(\eta_r) < H(\eta)$. Note that if $\eta_r = \boxplus$, then $H(\eta_r) < H(\eta)$ because $\mathcal{X}_{\text{stab}} = \boxplus$. The construction uses the six energy reduction mechanisms described in Sections 5.2.1–5.2.6 and relies on Propositions 5.6, 5.9, 5.12, 5.15, 5.17, 5.19, which are the key results of these sections. The maximal energy barrier in these propositions is $10U - \Delta_1$. *Note:* The energy reduction mechanisms in Sections 5.2.2 and 5.2.3 concern single droplets far away from $\partial^- \Lambda$ and have an energy barrier not exceeding $4U + \Delta_1 < \Gamma^*$ (see below (1.14)). For such configurations, the energy can be essentially reduced by saturating particles of type 2 and by adding and removing 12-bars. This explains the remark made in Section 1.4, item 4.

In the remainder of this section we call *supercritical* a 12-bar of length $\geq \ell^*$. Similarly, we call *supercritical* a dual rectangle with both side lengths $\geq \ell^*$.

Proof. As a preliminary step, perform the cleaning mechanism. If the outcome is \square , then the claim is proven. Otherwise, let b_1 be the first bridge encountered in the lexicographic order (which exists by Lemma 5.20). This bridge can be turned into an 12-bar \bar{b}_1 (see Section 5.2.3). If the length of b_1 is $< \ell^*$, then the 12-bar \bar{b}_1 can be removed, which lowers the energy (see Section 5.2.2). In this case, go back to performing the cleaning mechanism. W.l.o.g. we may therefore assume that the length of b_1 is $> \ell^*$.

By construction, all sites above \bar{b}_1 are empty, and therefore it is possible first to construct the 2-tiled rectangle $r_1 = \square(\bar{b}_1)$ within energy barrier $2\Delta_1 + 2\Delta_2 - 4U$ (again lowering the energy), and then expand r_1 to the rectangle $R_1 = \mathcal{R}^\top(r_1)$ (see Section 5.2.4). If the vertical side length of R_1 is $< \ell^*$, then R_1 can be removed (lowering the energy), and it is possible to perform again the cleaning mechanism.

Therefore suppose that R_1 has both its side lengths $\geq \ell^*$. In the remainder of the section we will show how to reach within energy barrier $10U - \Delta_1$ a configuration containing a rectangle R_{NW} touching both the north-side and the west-side of Λ^- whose support contains the support of R_1 . Once this has been achieved, it is possible to argue for R_{NW} in the same way as for R_1 in order to reach a configuration containing a rectangle R_{NWE} touching the north-side, the east-side and the west-side of Λ^- whose support contains the support of R_{NW} . Repeating the same argument for R_{NWE} , it is possible to reach \boxplus .

The construction of R_{NW} is obtained by using an algorithm called *invasion* of R_1 , which is constructed with the help of techniques similar to the ones that were used to build R_1 .

(A) Invasion of R_1 . See Fig. 22. Let (a_1, b_1) be, respectively, the horizontal and the vertical coordinate of the left lower-most particle of R_1 (which is of type 1). Define $\Lambda(R_1) \subset \Lambda$ to be the set consisting of the sites whose vertical coordinate is $\geq b_1$ and horizontal coordinate is $< a_1$. In words, $\Lambda(R_1)$ contains the sites of Λ on the left of R_1 . Perform the cleaning mechanism (see Section 5.2.6) and scan $\Lambda(R_1)$ in the lexicographic order. Three cases are possible.

1. $\Lambda(R_1)$ is empty. Add, if possible (R_1 might already be touching the west-boundary of Λ^-), 12-bars onto the left side of R_1 until the resulting cluster touches the west-boundary of Λ^- .
2. The first horizontal bridge b_2 encountered in $\Lambda(R_1)$ has length $< \ell^*$. Remove the particles of the (south)-support of the bridge, lowering the energy of the configuration, and restart the covering of $\Lambda(R_1)$.
3. The first horizontal bridge b_2 encountered in $\Lambda(R_1)$ has length $\geq \ell^*$. As for b_1 , first turn b_2 into the 12-bar \bar{b}_2 , then build the 2-tiled rectangle $r_2 = \square(\bar{b}_2)$, after that expand r_2 to $R_2 = \mathcal{R}^\top(r_2)$, and finally perform the cleaning mechanism. Note that the support of R_2 may cover (part or possibly all of) the support of R_1 . This means that during the maximal expansion, some of the sites of $\text{supp}(R_1)$ were in the support of the pillared beam that is going to be 2-tiled. Each time this happens, R_2 absorbs an entire vertical supercritical 12-bar of R_1 (see Section 5.2.4). Call \hat{R}_1 what is left of R_1

after the maximal expansion of R_2 . The following three cases are possible: (i) \tilde{R}_1 does not contain any particle ($\tilde{R}_1 = \emptyset$); (ii) $\tilde{R}_1 \prec R_1$ (in the proper sense); (iii) $\tilde{R}_1 = R_1$. In Case (ii), the rectangles R_2 and \tilde{R}_1 are necessarily adjacent (more precisely, the right-most 12-bar of R_2 is adjacent to the left-most 12-bar of R_1), whereas in Case (iii) the two rectangles may or may not be adjacent. Note that this implies that if $\tilde{R}_1 \prec R_1$, then R_2 is necessarily supercritical. Obviously, if $\tilde{R}_1 \neq \emptyset$, then it is again a 2-tiled rectangle, and there are several possibilities.

- (a) R_2 is not supercritical. This implies that $\tilde{R}_1 = R_1$. Remove R_2 from Λ , put $R_1 = \tilde{R}_1$ and restart the invasion of R_1 .
- (b) R_2 is supercritical and $\tilde{R}_1 = \emptyset$. Change the name of R_2 to R_1 and restart the covering of $\Lambda(R_1)$.
- (c) R_2 is supercritical and is adjacent to \tilde{R}_1 . Note that both rectangles touch the north-side of Λ^- . Call R^{\max} the rectangle with the largest vertical length (in case of a tie, w.l.o.g. choose R_1) and call R^{\min} the other rectangle. Slide R^{\min} onto R^{\max} . This is possible because the smoothing phase of the maximal expansion (see Section 5.2.4) removes all the particles of type 2 that may interfere with the sliding of the 12-bars. Then perform again the maximal expansion of R^{\max} , i.e., the rectangle that has not been moved during the sliding. These steps bring the configuration to a rectangle whose support contains $\text{supp}(R_2) \cup \text{supp}(R_1) \cup \Lambda(R_1)$. Call this rectangle R_1 and restart the invasion of R_1 .
- (d) R_2 is supercritical and is not adjacent to \tilde{R}_1 . This implies $\tilde{R}_1 = R_1$. Start the invasion of R_2 (see below).

In order to complete the proof, it remains to show how the invasion of R_2 carries over. To that end, we introduce the following *recursive algorithm* realizing the *invasion of R_i* for $i = 2, 3, \dots$, etc.

(B) Invasion of R_i . Call \bar{R}_{i-1} what is left of R_{i-1} after the invasion of R_{i+1} . There are three cases:

- I. $\bar{R}_{i-1} = \emptyset$ (i.e., the support of R_{i-1} is completely covered by R_i). Put $R_{i-1} = R_i$ and restart the invasion of R_{i-1} .
- II. $\bar{R}_{i-1} \neq \emptyset$ and R_i and \bar{R}_{i-1} are adjacent. Call R^{\max} the rectangle with the largest vertical side between R_i and \bar{R}_{i-1} (in case of a tie, w.l.o.g. choose $R^{\max} = R_i$) and call R^{\min} the other rectangle. Slide R^{\min} onto R^{\max} and perform the maximal expansion of R^{\max} . Call R_{i-1} the outcome of the maximal expansion of R^{\max} and restart the invasion of R_{i-1} .
- III. $\bar{R}_{i-1} \neq \emptyset$ and R_i and \bar{R}_{i-1} are not adjacent. If R_i is on the left of R_{i-1} , then let (a_i, b_i) denote, respectively, the horizontal and the vertical coordinate of the lower right-most particle (which is of type 1) of R_i , and call $\Lambda(R_i)$ the subset of $\Lambda(R_{i-1})$ consisting of those sites whose vertical coordinates are $\geq b_i$ and whose horizontal coordinates are $> a_i$. If R_i is on the right of R_{i-1} , then let (a_i, b_i) denote, respectively, the horizontal and the vertical coordinate of the lower left-most particle (which is of type 1) of R_i , and call $\Lambda(R_i)$ the subset of $\Lambda(R_{i-1})$ consisting of those sites whose vertical coordinates are $\geq b_i$ and whose horizontal coordinates are $< a_i$. In words, $\Lambda(R_i)$ consists of those sites of $\Lambda(R_{i-1})$ between R_{i-1} and R_i . Perform the cleaning mechanism and scan $\Lambda(R_i)$ in the lexicographic order. There are again several cases.
 - 1. $\Lambda(R_i)$ is empty. Call R^{\max} the rectangle with the largest vertical side between R_i and \bar{R}_{i-1} (in case of tie, w.l.o.g. choose $R^{\max} = R_i$) and call R^{\min} the other rectangle. Add vertical 12-bars on the side of R^{\min} facing R^{\max} until (depending on the parity of the rectangles) it becomes adjacent (different parity) to R^{\max} or it is at distance 1 (same parity) from R^{\max} . In the first case, slide the extended R^{\min} onto R^{\max} . Perform the maximal expansion of R^{\max} , and call R_{i-1} the rectangle obtained in this way, whose support contains $\text{supp}(R_i) \cup R_{i-1} \cup \Lambda(R_{i-1})$. Restart the invasion of R_{i-1} .
 - 2. The first horizontal bridge b_{i+1} encountered in $\Lambda(R_i)$ has length $< \ell^*$. Remove the particles of the (south)-support of the bridge, lowering the energy of the configuration, and restart the invasion of R_i .

3. The first horizontal bridge b_{i+1} encountered in $\Lambda(R_i)$ has length $\geq \ell^*$. First turn b_{i+1} into the 12-bar \bar{b}_{i+1} , then build the 2-tiled rectangle $r_{i+1} = \square(\bar{b}_{i+1})$, after that expand r_i to $R_{i+1} = \mathcal{R}^\top(r_{i+1})$, and finally perform the cleaning mechanism. Call \tilde{R}_i what is left of R_i after the maximal expansion of R_{i+1} . The following cases are possible.
 - (a) R_{i+1} is not supercritical. This implies $\tilde{R}_i = R_i$. Remove R_{i+1} from Λ , put $R_i = \tilde{R}_i$, and restart the invasion of R_i .
 - (b) R_{i+1} is supercritical and $\tilde{R}_i = \emptyset$. Change the name of R_{i+1} to R_i , and restart the invasion of R_i .
 - (c) R_{i+1} is supercritical and is adjacent to \tilde{R}_i . Note that both rectangles touch the north-side of Λ^- . Slide the rectangle with the shorter vertical length onto the other rectangle and perform again the maximal expansion of the rectangle that has not been moved during the sliding. These steps bring the configuration to a rectangle whose support contains $\text{supp}(R_{i+1}) \cup \text{supp}(R_i) \cup \Lambda(R_i)$. Call this rectangle R_i and restart the invasion of R_i .
 - (d) R_{i+1} is supercritical and is not adjacent to \tilde{R}_i . This implies $\tilde{R}_i = R_i$. Start the invasion of R_{i+1} .

The finiteness of Λ ensures that the algorithm eventually terminates. ■

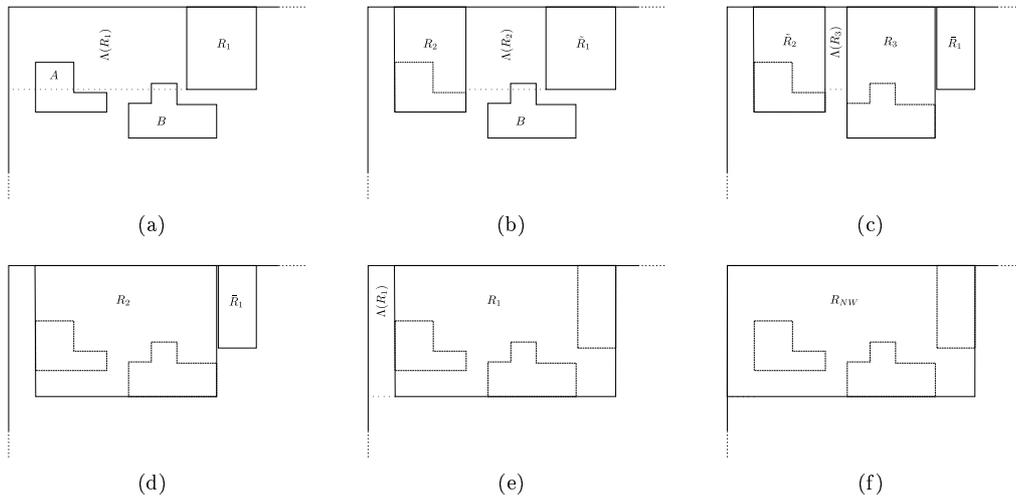


Figure 22: Example of invasion of the dual rectangle R_1 . Only the support of the relevant clusters are drawn and the parity of different clusters is not indicated. The set $\Lambda(R_1)$ contains a supercritical bridge belonging to cluster A (Fig. 22(a)). Growing this bridge via the construction of its northern rectangle and its subsequent maximal expansion leads to the supercritical rectangle R_2 (Fig. 22(b)). Next, the invasion of $\Lambda(R_2)$ has to be performed in order to complete the invasion of R_1 . The set $\Lambda(R_2)$ contains a supercritical bridge belonging to cluster B , which is grown into the supercritical rectangle R_3 (Fig. 22(c)). Note that R_3 partly covers the support of \tilde{R}_1 and that R_3 and \tilde{R}_1 are adjacent. The invasion of R_2 proceeds via the invasion of R_3 . Since $\Lambda(R_3)$ is empty, the invasion of R_3 is carried out by adding 12-bars to the left-side of R_3 until \tilde{R}_2 is at dual distance 1. After that a maximal expansion produces a dual rectangle that covers the support of \tilde{R}_2 (Fig. 22(d)). The new dual rectangle R_2 is adjacent to \tilde{R}_1 . The two rectangles are merged and a maximal expansion gives a new rectangle R_1 (Fig. 22(e)). Now $\Lambda(R_1)$ is empty and can be filled by adding 12-bars to the left-side of R_1 until the rectangle R_{NW} is obtained (Fig. 22(f)).

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